Reviews of Geophysics

Reanalysis in Earth System Science: Toward Terrestrial Ecosystem Reanalysis

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Abstract A reanalysis is a physically consistent set of optimally merged simulated model states and historical observational data, using data assimilation. High computational costs for modeled processes and assimilation algorithms has led to Earth system specific reanalysis products for the atmosphere, the ocean and the land separately. Recent developments include the advanced uncertainty quantification and the generation of biogeochemical reanalysis for land and ocean. Here, we review atmospheric and oceanic reanalyzes, and more in detail biogeochemical ocean and terrestrial reanalyzes. In particular, we identify land surface, hydrologic and carbon cycle reanalyzes which are nowadays produced in targeted projects for very specific purposes. Although a future joint reanalysis of land surface, hydrologic, and carbon processes represents an analysis of important ecosystem variables, biotic ecosystem variables are assimilated only to a very limited extent. Continuous data sets of ecosystem variables are needed to explore biotic-abiotic interactions and the response of ecosystems to global change. Based on the review of existing achievements, we identify five major steps required to develop terrestrial ecosystem reanalysis to deliver continuous data streams on ecosystem dynamics.

Plain Language Summary A reanalysis is a unique set of continuous variables produced by optimally merging a numerical model and observed data. The data are merged with the model using available uncertainty estimates to generate the best possible estimate of the target variables. The framework for generating a reanalysis consists of the model, the data, and the model-data-fusion algorithm. The very specific requirements of reanalysis frameworks have led to the development of Earth-compartment specific reanalysis for the atmosphere, the ocean and land. Here, we review atmospheric and oceanic reanalyzes, and in more detail biogeochemical ocean and terrestrial reanalyzes. In particular, we identify land surface, hydrologic, and carbon cycle reanalyzes which are nowadays produced in targeted projects for very specific purposes. Based on a review of existing achievements, we identify five major steps required to develop reanalysis for terrestrial ecosystem to shed more light on biotic and abiotic

interactions. In the future, terrestrial ecosystem reanalysis will deliver continuous data streams on the state and the development of terrestrial ecosystems.

1. Introduction

A reanalysis of a component of the Earth system provides a physically, chemically, and biologically consistent description of continuous past model states by merging multi-source observations and computational models (e.g., Balsamo et al., 2015; Bosilovich et al., 2008; Hersbach et al., 2020; Kalnay et al., 1996; Lorenz & Kunstmann, 2012; Saha et al., 2010). Reanalyzes in Earth system science provide extremely valuable data sources on the past states of (components) of the Earth system, like the atmosphere and ocean. These reanalyzes can serve as input for other model calculations (e.g., land surface models forced by atmospheric reanalysis data), lead to increased process understanding, provide data for states and fluxes which cannot be directly observed and are also valuable data sources for industry and policy. While atmospheric and ocean reanalysis have a tradition dating back to the 1970s (e.g., Bengtsson et al., 1982; "Planning for First Garp Global Experiment (Fgge)," 1972), reanalyzes for terrestrial processes such as land-atmosphere interaction (Section 2.3), hydrology (Section 2.4), and terrestrial carbon cycling (Section 2.5) has only recently gained traction. The most recent developments in biogeochemical reanalysis are of particular importance for ecosystem science as these reanalyzes focus more on life-supporting biotic processes at the Earth's surface.

Knowledge on ecosystem change, management of ecosystems and ecosystem functions are important to society as ecosystems provide invaluable services to humanity such as denaturing pollutants, improving water quality, food production, resistance to pest and disease, mitigating climate change and enhancing soil resilience (Costanza et al., 1997; Lal, 2015). Natural and managed ecosystems are complex, structured systems composed of living (biotic) and non-living (abiotic) components. Abrupt climate change and human induced land use changes are inducing strong pressures on the environment and are diminishing ecosystem values and services (Kubiszewski et al., 2017; Vitousek et al., 1997). Acknowledging and estimating the value of ecosystem services to society and its sustainable development goals (SDGs) are important (Wood et al., 2018) and an essential prerequisite to counteracting negative impacts of anthropogenic activities, leading to more sustained ecosystem management and application of nature based solutions (Guerry et al., 2015; Motesharrei et al., 2016; Rosa et al., 2020). Forecasting the Earth and ecosystem behavior under global change requires an understanding of the key processes controlling ecosystem changes, which is subsequently indispensable for designing and implementing measures and actions to meet the SDGs. A clear analysis of past and current states and dynamics of ecosystems are also critical to forecasting future scenarios (Bonan & Doney, 2018; Rosa et al., 2020).

Terrestrial ecosystem reanalysis aims to provide this analysis of past and current states of the ecosystem. A terrestrial ecosystem reanalysis is a continuous set of states and fluxes (and possibly parameters) of the interacting biophysical compartments of the ecosystems, holistic, and coherent to the model used and including mechanistic process representation. It provides a model-data-driven initialization for the assessment of the future ecosystem development under scenarios of global change. The system descriptions underlying the existing land surface, carbon and hydrologic cycles models also provide a basis for developing a conceptual description of a terrestrial system reanalysis by linking the individual models. Terrestrial ecosystem reanalysis goes beyond current state-of-the-art land surface, hydrologic, and carbon cycle reanalysis by also turning biotic ecosystem observations and Earth observation data into continuous ecologically meaningful maps. An ecosystem reanalysis bridges the gap between remote sensing products, *in situ* observation networks common in biodiversity research and a terrestrial ecosystem model with different availabilities and quality of observation data over the historical period considered. Examples of such in situ observations suitable for assimilation are above- and below-ground biomass, crop yield, net ecosystem exchange, and plant traits composition, and examples of remotely sensed observations are leaf area index, canopy height, and aboveground biomass, gross primary production and plant phenology. We distinguish model-data fusion-based reanalyzes from data-driven reconstructions that use correlation, interpolation and analysis techniques to create best estimates. In contrast to reanalysis, such data-driven reconstructions do not fuse the data with a model along the simulation period.

Data assimilation methods or model-data fusion methods optimally combine Earth system models and observations in a Bayesian sense. They constitute the methodologic basis for reanalysis of the Earth system provided with datasets and products consistent with the underlying physical, chemical and biological principles (Bennett & Budgell, 1987; Evensen, 2003; Kalnay, 2003). Uncertainty in reanalysis products is explicitly considered depending on the data assimilation method. For example, with an ensemble-based data assimilation approach, different model trajectories are calculated which are all consistent with past measurement data. Uncertainty estimates can be derived from the ensemble statistical measures of the model (e.g., variances, covariances). Model-data fusion methods are also an essential ingredient of now- and forecasting systems of which ecological forecasting has gained significant traction in recent years (Dietze, 2017). Adjoined to ecosystem reanalysis, ecological forecasting is defined to be the prediction of ecosystem states, services, and natural capital with quantified uncertainty under global change (J. S. Clark et al., 2001).

In this study, we aim to outline possible ways forward toward developing a framework for continental scale terrestrial ecosystem reanalysis. For this, we review briefly the state-of-the-art of reanalysis in Earth system sciences (Section 2). Section 3 discusses model-data-fusion methods that have been used in Earth system sciences and reanalysis. In Section 3 we also address the computational requirements for long-term data storage and the reanalysis. Section 4 formulates a roadmap toward "terrestrial ecosystem reanalysis" as a short-term objective, outlining a few opportunities. This review also intends to stimulate cross-disciplinary community building involving ecologists, hydrologists, meteorologists, and soil scientists toward a stronger coupling of water, energy and biogeochemical cycles in terrestrial and ecosystem modeling.

2. Status of Reanalysis in Earth Sciences

Research on reanalysis in Earth systems is growing rapidly (Figure 1a). Increasing computational capabilities, the growing availability of long-term satellite data with global coverage, advancements in model-data fusion methods such as variational and sequential data assimilation and the increasing awareness of the drastic changes in the Earth system related to anthropogenic and climatic factors drive reanalysis development. This is not only the case for atmospheric sciences, but more recently and more rapidly in hydrologic and ecosystem research, here in the sense of combining reanalysis with soil, hydrologic, biodiversity, and carbon research (Figure 1a). The analysis of recent scientific publications indicates an above-average increase in publications in hydrologic-, carbon cycle-, soil-, and vegetation reanalysis. Reanalysis started in atmospheric science since the launch of the first satellite missions in the 1960s and 70s, succeeded by more than 12,839 publications in meteorology and atmospheric sciences alone. Although atmospheric research still accounts for 43% of published research on reanalysis, research on other Earth system compartments adopted the reanalysis concept to generate continuous, consistent time series used to detect trends, and analyze past states (Figure 1b). Existing reanalysis approaches focus either on specific compartments (atmosphere, land, and ocean) of the Earth system including the interface such as vegetation, or on matter cycles such as carbon, water, and nutrients (Figure 2). Internal feedbacks in the geophysical system are enclosed in a data assimilation framework. Reanalyzes considered in this review are ideally global-scale or continental-scale high-resolution products. They represent a temporally high-resolution description of a coherent geophysical system. Data in Table 1 gives an overview on recent exemplary reanalysis products with a length of at least 5 years and the data being available under FAIR (Findable, Accessible, Interoperable, and Reusable) principles (M. D. Wilkinson et al., 2016). Details of the methodological approach for a data assimilation system are described in Section 3. The reanalysis product depends on the model complexity and data availability (Figure 3). In the next section, we summarize the main achievements and the reanalysis concepts used in the different components of Earth sciences with emphasis on the most recent developments in relation to ecosystem science.

2.1. Atmospheric Reanalysis

Atmospheric reanalysis refers to the consistent incorporation of various observations into a numeric weather prediction model using sequential or, more typically, variational data assimilation techniques, with the aim of providing best possible estimates of past atmospheric states (e.g., Kalnay et al., 1996; S. Uppala et al., 2008; Wahl et al., 2017). An important aspect of reanalysis products is that the model system and
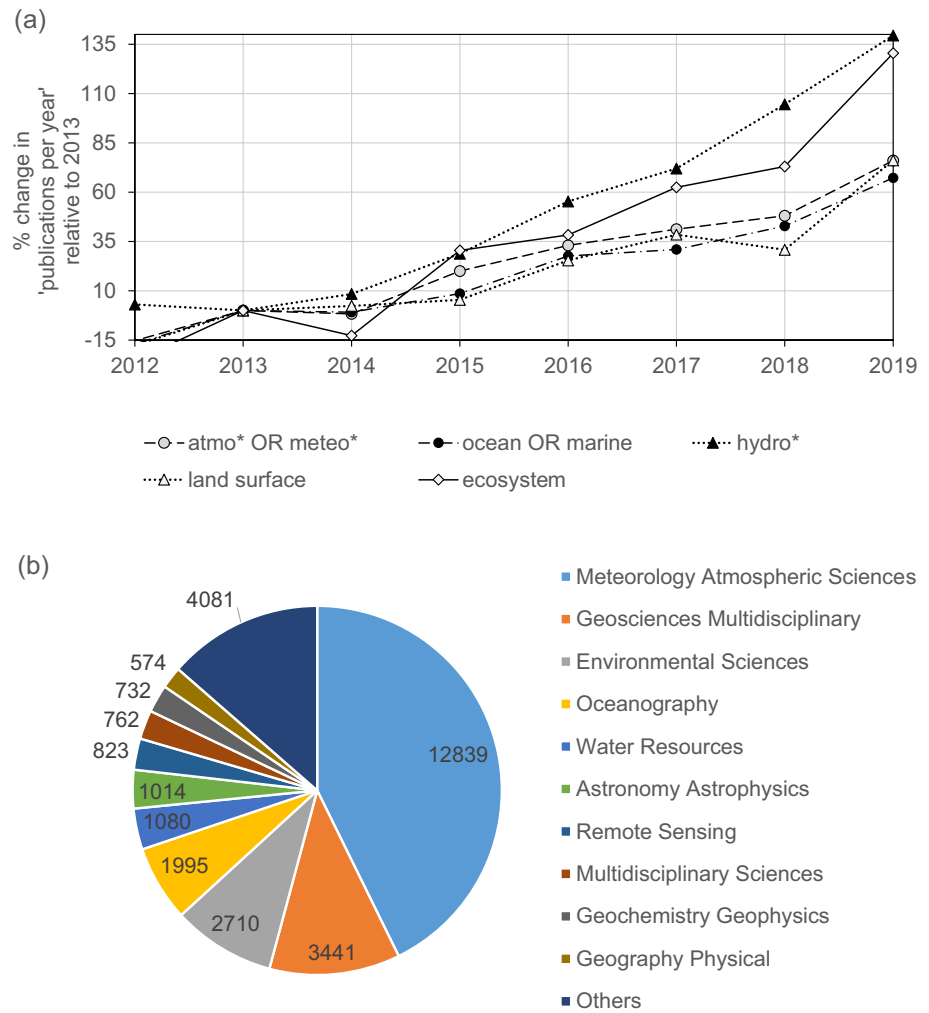
Figure 1. Literature review on reanalysis in different Earth system compartments. Results are based on keyword search in https://apps.webofknowledge.com on February 26, 2021. Panel (a) shows publication growth rate of individual science domains from 2013 to 2019, relative to the year 2013. Highest growth rates occurred for hydrological research (139%, 316 publications in 2019, keywords "hydro × and reanalysis"), and ecosystem research (130%, 325 publications in 2019, keywords "(ecosystem OR carbon OR vegetation OR biodiversity OR soil) AND reanalysis"). Rates outperform those of total publication output (30%, not shown) and that of "reanalysis" alone (48%, not shown). Panel (b) shows publications associated to "reanalysis" and the "Web of Science Categories", respectively.
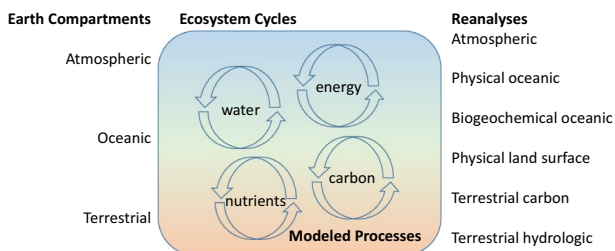
Figure 2. Concept of existing reanalysis approaches relative to earth system compartments and physical (water and energy) and biogeochemical ecosystem cycles (water, energy, nutrients, and carbon). Reanalyzes at process level beyond individual compartments is weak, hence remains a scientific challenge.

the data assimilation procedure do not change during the time period of the reanalysis. In contrast, uncertainty characteristics of the assimilated measurement data do change, which is related to the changing technical specifications of observation systems deployed. Currently 7–9 million observations are assimilated at each time step in global atmospheric reanalysis systems and include for example, observations made at the dense global network of meteorological stations, ships, and buoys, information from a large number of satellites, vertical soundings and aircraft.

In the US, the National Center of Environmental Prediction (NCEP) and National Center for Atmospheric Research (NCAR) collaborate on the provision of atmospheric reanalyzes (See Table 1). They produced a first global reanalysis for the period 1957–1996 (Kalnay et al., 1996), which was extended later for the period since 1948 and is still updated, covering now the period 1948–2018. This reanalysis is produced with the global

Table 1
Overview of Exemplary Reanalysis Products in the Earth System Domains and Key Characteristics (See Excel)

	Reanalysis product	Lead organization	Data portal	Supporting entity	Time period	Spatial resolution	Spatial extent	Assimilation method	Reference	Vertical Resolution
Oceanic	ORAS5	ECMWF	Yes	University of Hamburg ICDC	1979–present	1/4°	Global	3D-Var	Zuo et al. (2019)	75 levels
Oceanic	SODA3	NCAR/NOAA/NODC	No	Authors	1979–present	1/4°	Global	Optimal interpolation	Carton et al., (2018)	50 levels
Oceanic	ECCOV4.3	MIT	Yes	NASA Earth Data	1992–2015	Variable	Global	4D-Var	Forget et al. (2015)	50 levels
Oceanic	GLORYS12V1	Mercator Ocean	Yes	Copernicus	1993–2019	1/12°	Global	SEEK+3DVar	Drevillon et al. (2018)	50 levels
Oceanic	CERA-20C	ECMWF	No	ECMWF	1900–2010	~120 km	Global	Variational	Laloyaux et al. (2018)	variable
Oceanic	NWSOC-REA	PML-NCEO	Yes	PML Data Portal	1998–2009	~12 km	Regional	EnKF	Ciavatta et al. (2016)	42 levels
Oceanic	MedPFT-REA	PML-NCEO	Yes	PML Data Portal	1998–2014	1/10°	Regional	EnKF	Ciavatta et al. (2019)	42 levels
Oceanic	NWSHELF_MULTIYEAR_BGC_004_011	Met Office	Yes	Copernicus	1993–2019	~1/10°	Regional	3D-Var	Skakala et al. (2018)	24 levels
Oceanic	MEDSEA_REANALYSIS_BIO_006_008	OGS	Yes	Copernicus	1999–2018	0.06°	Regional	3D-Var	Teruzzi et al. (2019)	72 levels
Atmospheric	JRA-55	JMA	Yes	NCAR, DIAS	1958–2013	55 km	Global	4DVar	Kobayashi (2015)	60 levels
Atmospheric	ERA5 (successor to ERA-Interim)	ECMWF	Yes	CDS Copernicus	1979–2019	30 km	Global	4D-Var	Hersbach et al. (2020), Dee et al. (2011)	137 levels
Atmospheric	ERA-20C	ECMWF	No	ECMWF	1899–2009	125 km	Global	4D-Var	Poli et al. 2015	37 atm levels
Atmospheric	40 years Reanalysis Project	NCEP/NCAR	No	ECMWF	1957–1996	210 km	Global	3DVar	Kalnay et al. 1996	28 atm levels
Atmospheric	CSFR	NCEP/NCAR	Yes	NCAR	1979–2010	0.5°	Global	3DVar (modified)	Saha et al. 2010	64 atm levels
Atmospheric	20CRV3	NOAA–CIRES–DOE	Yes	NOAA	1836–2015	1°	Global	EnKF	Compo et al. (2011), Slivinski et al. (2021)	64 levels
Atmospheric	Arctic System Reanalysis	Ohio State University	Yes	Authors	2000–2012	15 km	Regional	3DVAR	Bromwich et al. (2018)	71 atm levels
Atmospheric	COSMO-REA2	DWD	No	DWD	2007–2016	2km	Regional	Continuous Nudging	Wahl et al. (2017)	50 atm levels
Atmospheric	COSMO-REA6	DWD	No	DWD	1995–2017	6km	Regional	Continuous Nudging	Bollmeyer et al. (2015)	40 atm levels
Atmospheric/ land surface	MERRA-2 (successor to MERRA and MERRA/Land)	NASA	Yes	MDISC–GES	1979–present	~0.5°	Global	3DVAR	Gelaro et al. (2017), Rienecker et al. (2011)	72 levels

Table 1
Continued

Reanalysis product	Lead organization	Data portal	Supporting entity	Time period	Spatial resolution	Spatial extent	Assimilation method	Reference	Vertical Resolution
Terrestrial (land surface)	GLDAS	NASA/GSFC/NOAA	Yes	MDISC–GES	2003–present	0.25°–2.5°	Global	EnKF	Rodell et al. (2004), Kumar et al. (2019)	14, plus snow/veg.
Terrestrial (land surface)	ERA5/Land	ECMWF/Copernicus	Yes	CDS Copernicus	1981–present	9km	Global	4DVar	Muñoz Sabater (2019)	4, plus snow/veg.
Terrestrial (land surface)	ESSMRA	Forschungszentrum Jülich	Yes	Authors	2000–2015	3km	Regional	EnKF	Naz et al. (2020)	10 levels
Terrestrial (land surface/carbon)	SMAP Level-4	NASA/GMAO	Yes	NASA	2015–present	9km	Global	Distributed EnKF	Reichle et al. (2016, 2019); Jones et al. (2017)	–
Terrestrial (carbon)	CARDAMOM	University of Edinburgh	Yes	Authors	2001–2010	1°	Global	Adaptive Metropolis MCMC	Bloom and Williams (2015)	–
Terrestrial (carbon)	CARDAMOM pantropical retrievals 2000–2015	University of Edinburgh	Yes	Authors	2000–2015	1°	Regional	Adaptive Metropolis	Exbrayat and Williams (2018)	–
Terrestrial (hydrology)	Global Water Cycle Reanalysis	Center for Water and Landscape Dynamics	No	Authors	2003–2012	1°	Global	own approach	van Dijk et al (2014)	–
Terrestrial (hydrology)	Global Water Cycle	NASA	Yes	GESDISC	2000–2010	1°	Global	own approach	Rodell et al. (2015)	–
Terrestrial (hydrology)	GRUN	ETH Zürich	No	Authors	1902–2014	0.5°	Global	MCMC (Data Fusion)	Ghiggi et al. (2019)	–
Terrestrial (hydrology)	Continental Runoff into the Oceans	University of Washington	No	Authors	1950–2008	1°	Global	own approach (Data Fusion)	Clark et al. (2015)	–
Terrestrial (hydrology)	DOLCE	CCRC	Yes	NCI Australia	2000–2009	0.5°	Global	own approach (Data Fusion)	Hobeichi et al. (2018)	–
Terrestrial (hydrology)	CDR	Princeton University	Yes	NCAR	1984–2010	0.5°	Global	own approach (Data Fusion)	Zhang et al. (2017)	-
Terrestrial (hydrology)	GRACE-REC	ETH	No	Authors	1901–2019	0.5	Global	MCMC (Data Fusion)	Humphrey and Gudmundsson (2019)	–

Abbreviations: CARDAMOM, Carbon Data Model Framework; ECMWF, European Center for Medium-range Weather Forecasts; ESSMRA, European Surface Soil Moisture ReAnalysis; GRACE, Gravity Recovery and Climate Experiment; JMA, Japanese Meteorological Agency; MCMC, National Center for Atmospheric Research; NCAR, National Center for Atmospheric Research; NCEP, National Center of Environmental Prediction; ORAS5, Ocean ReAnalysis System 5; SMAP, Soil Moisture Active Passive;
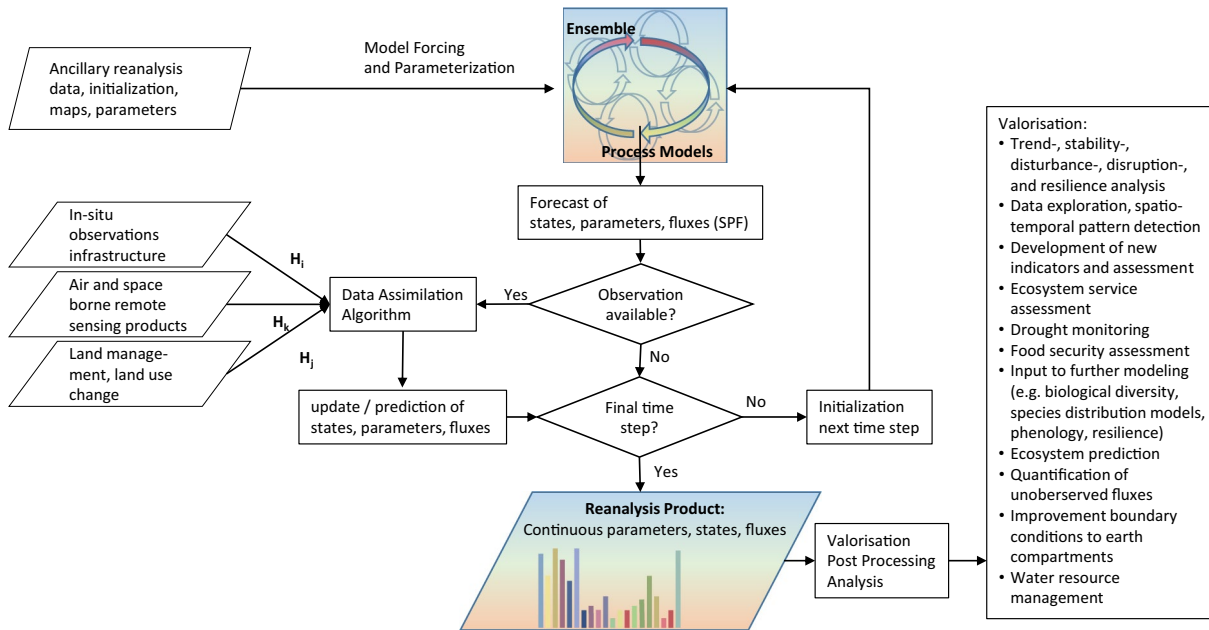
Figure 3. Flow chart on creation and valorization of an Earth system reanalysis product, model-data-fusion scheme, uncertainty propagation, and time-step iterative data assimilation.

circulation model Global Forecast System (GFS) and 3D variational data assimilation (3DVAR), at a spatial resolution of 2.5° and for 28 atmospheric levels. Later the so-called Climate Forecast System Reanalysis (CSFR) was published by NCEP, which provides the reanalysis products at a much higher spatial resolution of 0.5° and 64 atmospheric levels for the period 1979–2010 (Saha et al., 2010). The main innovation of this new product is that it considers the coupled atmosphere-ocean-ice-land system, and includes variations in CO_2-concentrations, aerosol concentrations and solar activity (Saha et al., 2010). The data assimilation itself is uncoupled which means that measurement-based updates for the atmospheric and ocean compartments of the model are made independently. The modified 3DVAR assimilation system adopted a new model error variances rescaling (Kleist et al., 2009), acknowledged trends in observational data through first-order temporal extrapolation and had quality control algorithm implemented on innovation and variances (Andersson & Jarvinen, 1999).

Regional atmospheric reanalysis can go to even higher resolutions with potential advantages to coarse scale global reanalysis. The Central European COSMO_REA2 operates at 2 km horizontal grid resolution (Wahl et al., 2017), performing convective scale atmospheric prediction by assimilating surface and radar precipitation. ERA-Interim drives the COSMO_REA2 reanalysis as is the case for the COSMO_REA6 reanalysis (Bollmeyer et al., 2015). COSMO_REA6 spans a larger time span while assimilating data from radiosondes, aircrafts, wind profiler, and synoptic surface observations. Both central European reanalyzes show improved representation of high resolution precipitation prediction compared to ERA-Interim. The regional Arctic System Reanalysis (ASR) focused on improving representation of physical processes over frozen surfaces using the Polar Weather Research and Forecasting model (WRF, Powers et al., 2017) with ERA-Interim again providing lateral and initial conditions. Operated at 15 km horizontal resolution, ASR assimilates a multitude of on-ground, air, sea, and satellite observations during the time period 2000–2012. The updated model physics such as subgrid-scale cloud fraction interaction improved correlation and reduced biases in short wave and long wave radiation, seasonal arctic precipitation, and 10 meter wind speed observations (Bromwich et al., 2018).

The European Center for Medium-range Weather Forecasts (ECMWF) published its second global atmospheric ECMWF Re-Analysis (ERA40, S. Uppala et al., 2008) in 2004. The successor of the 15 years ERA15 reanalysis (Gibson et al., 1997) was produced for a 45 year period (1957–2002) at a resolution of 1.125° and for 60 atmospheric levels, using its ECMWF-model in combination with 3DVAR. It was the first atmospheric reanalysis where low product level satellite data were directly assimilated instead of variable retrievals (S.

Uppala et al., 2008). An improved product, ERA-Interim, followed relatively soon thereafter, providing reanalysis at a higher spatial resolution (0.75°), and improved data assimilation with 4DVAR (Dee et al., 2011). Recently, a new ECMWF-reanalysis product, ERA5, has been made available, which is at yet another higher spatial resolution of 0.25° (Hersbach et al., 2020). The main innovation is that coupled data assimilation for the atmosphere-land is used. In addition to atmospheric observations, ERA5 assimilates remotely sensed soil moisture from the ASCAT satellite, snow information, and screen level meteorological measurements. The ERA5 reanalysis is available in near real-time with a few days delay. The near real time data is released as ERA5T data which becomes ERA5 data after 2–3 months lag time. The lag time ensures an option for intervention in the rare event that errors are identified in the near real time window. Some studies showed that the ERA5 reanalysis product outperforms other reanalysis products, for example, on the basis of comparison with precipitation datasets (e.g., Beck et al., 2019). Another important product is ERA-20C, an atmospheric reanalysis for the complete 20th century until 2011, at 125 km (~1.25°) spatial resolution, and also produced with 4DVAR (Poli et al., 2015). In this product no upper atmosphere information and satellite information was assimilated, as this information was not available in the beginning of the 20th century. ERA-20 C does therefore not provide the best estimates of the atmospheric states in the late 20th century and beginning of the 21st century, as for this more recent period ERA5 is a better product. Within this context, NOAA-CIRES-DOE Twentieth Century Reanalysis (20CRv3) project reconstructed four-dimensional global atmospheric states and associated uncertainties using an 80 member ensemble Kalman filter providing three-hourly data from 1806 to 2015 (Compo et al., 2011; Slivinski et al., 2019). Assimilated observations of the era before 1900 are Arctic sea ice extent and sea level pressure. The century long reanalyzes provide means to analyze recent trends in atmospheric circulation patterns in a historical perspective.

Another global reanalysis, the Japanese 55-years Reanalysis JRA-55, is provided by the Japanese Meteorological Agency (JMA), for the period since 1957 and until the near present (with a few days delay). JRA-55 combines the JMA forecast model and 4DVAR (Harada et al., 2016; Kobayashi et al., 2015). JRA-55 succeeded the JRA-25 which provided a reanalysis from 1979 to 2004 (Onogi et al., 2007). Three products are delivered in the context of JRA-55: besides the full-blown reanalysis also a reanalysis is made using only conventional observations and an open loop run without data assimilation (Kobayashi et al., 2015). Finally, MERRA-2 is a global atmospheric reanalysis produced by NASA global modeling and assimilation office (Gelaro et al., 2017). A key strength is the high spatial (0.5°, 72 atmospheric levels) and temporal (hourly) resolution at the global scale and the fact that it is oriented more toward an Earth System Reanalysis, with better representation of land and sea ice processes. For further details on MERRA-2 development see Section 2.3.

Despite the enormous advances in atmospheric reanalysis, the products still have some important limitations. One main problem is the presence of temporal discontinuities due to production stream transitions and changes in the observing systems. This implies, for example, that the detection of trends from reanalyzes must be interpreted cautiously (B. Y. Chen & Liu, 2016; Hobbs et al., 2020; Kossin, 2015). Another main problem is the strong dependency on parameterizations resulting, for example, in unreliable rainfall estimates in convection-dominated regions (Beck et al., 2019). Important ecosystem variables such as soil moisture are considered as tuning variables and outcome of atmospheric processes, which is one reason for often well represented trends but significant differences in magnitude between soil moisture data from reanalysis and remotely sensed or in-situ observations (Rotzer et al., 2015; Yang et al., 2020).

2.2. Ocean Reanalysis

Ocean reanalyzes assimilate historical marine observations into models that represent a range of processes from hydrodynamic and sea ice dynamics to biogeochemical reactions and complex trophic interactions of the marine food web. Ocean reanalysis is of particular interest in this review, because ocean reanalysis has progressed further in including ocean ecosystem variables compared to terrestrial reanalysis. Historically, ocean reanalysis has been synonymous with retrospective analysis of physical properties (e.g., water temperature, salinity, current velocities, Penny et al., 2019) using concepts and methods from atmospheric sciences, with the main objective of investigating climate signals and feedbacks (Bengtsson & Shukla, 1988). Since the seminal decadal reanalysis (1982–1992) of sea surface temperature in the Pacific by (Ji et al., 1994), the delivery of ocean physics reanalysis products has become well established in many operational and research

centers (Balmaseda et al., 2015). Current state-of-the-art physical ocean reanalyzes include (see Table 1 and Carton et al., 2018) ORAS5 (Ocean ReAnalysis System 5 by the European Center for Medium-Range Weather Forecasts, ECMWF; Zuo et al., 2019), SODA3 (Simple Ocean Data Assimilation, version 3; Carton et al., 2018), ECCO4r3 (Estimating the Circulation and Climate of the Ocean, version 4, release 3; Forget et al., 2015) and GLORYS12V1 (Global Ocean reanalysis and Simulation, version 2 by Mercator Ocean; Lellouche et al., 2018).

ORAS5 is a reconstruction of the ocean and sea-ice state extending back to 1958. ORAS5 was produced with the global ocean-sea ice model with a 1/4° horizontal resolution. The system uses a 3D-Var system to assimilate 5-daily satellite sea surface temperature (SST), sea level anomalies (SLA), sea ice concentration and subsurface temperature and salinity profiles.

SODA3 is a reconstruction of the ocean and sea-ice state that covers the period from 1980 onwards. SODA3 was produced using the global Modular Ocean Model component of the GFDL CM2.5 coupled model and includes an interactive sea ice model. An optimal interpolation system assimilates 10-daily satellite SST and subsurface temperature and salinity profiles.

ECCO4r3 is a reconstruction of the ocean and sea-ice state that covers the period from 1992 to 2015 using the MITgcm. ECCO4r3 employs a 4D-Var method to assimilate SLA, surface salinity, and time-dependent gravity.

GLORYS12V1 reconstructs the ocean and sea-ice state for 1993–2019, characterized by a particularly high spatial resolution (1/12°). It was produced using the NEMOv3.1 ocean model coupled to the LIM2 sea-ice model and used the Singular Extended Evolutive Kalman (SEEK) filter with 3DVar bias correction to assimilate SLA, sea ice concentration, SST, and in situ profiles of temperature and salinity.

Recent advances in coupled data assimilation systems led to reanalysis activities beyond just the physical ocean state. For example, CERA-20C (Laloyaux et al., 2018) is a coupled Earth system reanalysis of the 20th century (1901–2010) reconstructing past weather and climate in the atmosphere, as well as the state of the ocean, land, ocean waves, and sea ice. The model couples the ECMWF's Integrated Forecasting System (IFS) for the atmosphere, land, and waves to the NEMO model for the ocean and to the LIM2 model for sea ice. A variational method with a common 24-h window shared by the atmospheric and ocean components is used to assimilate SLA and marine wind observations as well as ocean temperature and salinity profiles.

Reanalyzes of the ocean chemical and biological components have become available only more recently because of the many unknowns in ecosystem functioning, the sparsity of relevant ocean observations, and high non-linearity of the model equations that challenges traditional Gaussian assumptions in data assimilation methods (Fennel et al., 2019). Early work on biogeochemical data assimilation by (Ishizaka, 1990) capitalized on the availability of large-scale and relatively high-frequency ocean color observations. It was almost 20 years later that the first multi-annual biogeochemical reanalyzes were produced by assimilating ocean-color total chlorophyll in the global ocean (Nerger & Gregg, 2008), in an ocean basin (Fontana et al., 2013) and in coastal and shelf-seas ecosystems (Ciavatta et al., 2016; Hu et al., 2012). More recent contributions include the decadal global ocean ecosystem reanalyzes by Ford and Barciela (2017), obtained by assimilating two different ocean color products for 1997–2012, and the one by Gregg and Rousseaux (2019), who estimated global trends of primary production by assimilating ocean color for 1998–2015.

Besides the well-established assimilation of total chlorophyll from ocean-color (e.g., Hu et al., 2012), innovative applications have assimilated surface ocean color products for: spectral diffuse attenuation coefficients (Ciavatta et al., 2014), size-fractionated chlorophyll and particulate organic carbon (POC; Xiao & Friedrichs, 2014), remote sensing reflectance (E. M. Jones et al., 2016) and both phytoplankton functional type chlorophyll and spectral absorption (Ciavatta et al., 2018, 2019; Pradhan et al., 2019; Skakala et al., 2020). Surface data of partial pressure of CO_2 (pCO_2) from ships of opportunity were used in the reanalysis of air-sea CO_2 fluxes in the global ocean (While et al., 2012). For the ocean interior, biogeochemical simulations were improved by assimilating vertical observations of nutrients, oxygen, and pCO_2 data at fixed stations (Allen et al., 2003; Gharamti et al., 2017), glider data of chlorophyll and POC (Kaufman et al., 2018) and biogeochemical-Argo float profiles of oxygen, chlorophyll, photosynthetically available radiation, phytoplankton biomass, and POC (Cossarini et al., 2019; Terzic et al., 2019; Verdy & Mazloff, 2017;

B. Wang et al., 2020). Thus far only few applications addressed weakly versus strongly coupled assimilation of both biogeochemical and physical data but showed these helped to preserve the consistency between physical and biogeochemical structures (Song et al., 2016; Yu et al., 2018). The integrated assimilation of both physical and biogeochemical observations from both satellite and in situ platforms is an active area of research and the likely way forward in marine ecosystem reanalysis (Skákala et al., 2021).

Currently, ocean ecosystem reanalyzes assimilating biogeochemical data are delivered operationally by several centers of the European Copernicus Marine Environment Monitoring Service: in the North West European Shelf and Mediterranean Sea, by assimilating ocean-color with 3DVar methods (Skakala et al., 2018; Teruzzi et al., 2014), and in the Arctic Sea, by assimilating ocean-color with a deterministic Kalman filter. These reanalyzes are finding applications in Blue Growth, management and policy, besides in the delivery of periodical assessments of the state of the ocean (von Schuckmann et al., 2020).

2.3. Land Surface Reanalysis

Land surface reanalysis focusses on land-atmosphere states and exchange, that is, mass and energy fluxes between the land surface, vegetation, and the atmosphere. Atmospheric reanalyzes can also provide modeled states and fluxes at the land-atmosphere intersection, which can be tuned to match synoptic observations at meteorological stations, or use land-surface reanalyzes data as lower boundary condition. Land surface states and fluxes are important boundary conditions to hydrologic, ecologic and atmospheric process models. Frequently assimilated variables in land surface reanalysis products are precipitation, soil temperature, soil moisture, snow extent, depth, and snow water equivalent. Most if not all land surface reanalysis are forced with either regional or global atmospheric reanalysis.

One of the earliest systems aiming to assimilate land surface data is the Global Land Data Assimilation System (GLDAS; Rodell et al., 2004). Different GLDAS products exist where the terrestrial processes are modeled with different land surface models: the Noah land surface model (Niu et al., 2011), the Community Land Model version 2 (Bonan et al., 2003), Catchment land surface model (Koster et al., 2000; R. H. Reichle et al., 2011) and the Variable Infiltration Capacity model (VIC; Liang et al., 1994). Although developed for data assimilation, only GLDAS version 2.2 assimilates total water storage of the Gravity Recovery and Climate Experiment satellite mission (GRACE) in the Catchment model (Li et al., 2019). A few of the most common land surface models used in terrestrial reanalysis and data assimilation studies, and represented processes are characterized in Table 2. All land surface models in GLDAS are parameterized by satellite based remotely sensed maps of vegetation, land cover classes, leaf area index, soil properties, elevation and slope. Leaf area index climatology and vegetation parameters are based on 1 km satellite derived information, fractions determine subgrid variability and serve as input to the land surface model run at vertically resolved sub-grid columns.

The Modern-Era Retrospective Analysis for Research and Applications (MERRA; Rienecker et al., 2011) was enhanced toward the land surface reanalysis MERRA-Land by R. H. Reichle et al. (2011) through scaling in-situ precipitation observations with MERRA precipitation, and the revised land surface parameters of the Catchment land surface model (Koster et al., 2000; R. H. Reichle et al., 2011). The Catchment model simulates horizontal surface, subsurface, and runoff water fluxes based on sub-grid topography, bulk soil moisture, land surface heterogeneities, resolved runoff generating processes in addition to the vertical physical water transport which is common to the regular grid based land surface models. The MERRA-Land particularly focused on improving precipitation information for hydrologic land surface and water budget applications. Rienecker et al. (2011) identified the most pressing challenges being the improved representation of surface fluxes and precipitation, and the reanalysis product itself being strongly sensitive to observations. MERRA-Land therefore uses a larger amount of in-situ precipitation to interpolate at grid scale. These findings guided the development of MERRA-2, the successor to MERRA-Land and MERRA. MERRA-2 yields an improved reanalysis of precipitation due to the larger amount of land surface data assimilated, and more abundant hydrologic processes considered in the Catchment land surface model (R. H. Reichle, Draper, et al., 2017).

ECMWF also developed the ERA-Interim/Land reanalysis product (Balsamo et al., 2015). ERA-Interim/Land builds upon the ERA-Interim atmospheric reanalysis by additionally incorporating in-situ

precipitation measurements in the assimilation system, and improved land surface parameterization forced by the offline atmospheric reanalysis. Land surface variables such as soil temperature, soil moisture, and snow depth were not assimilated yet but mostly used for assessing the reanalysis skill. The recent ERA5/land reanalysis product from ECMWF, where weakly coupled atmosphere-land data assimilation was performed, assimilates satellite surface soil moisture, and snow cover information (Hersbach et al., 2020). The ERA5 reanalysis is downscaled to 9 km for the ERA5/Land product and incorporates an updated model parameterization for the Hydrology-Tiled ECMWF Scheme for Surface Exchanges over Land (HTESSEL; van den Hurk & Viterbo, 2003) for the period 2000–2019. Similar to previous reanalysis, the ERA5/land uses a multi-year satellite based vegetation climatology (Boussetta et al., 2013), soil mass and energy fluxes, and a snow model (Dutra et al., 2010). A lapse-rate correction maps the output of the ERA5 atmospheric reanalysis to the altitude and interface of the land surface forcing.

Another operational global scale land surface reanalysis that initially was conceived to add value to the Soil Moisture Active Passive (SMAP) mission satellite mission, is the SMAP Level 4 surface and root-zone soil moisture product (R. Reichle et al., 2016; R. H. Reichle et al., 2019). SMAP L4_SM assimilates the SMAP observations into the Catchment land surface model. Being only available since the launch of the SMAP mission in 2015, the SMAP L4_SM product represents the global terrestrial reanalysis with a high spatial resolution. The SMAP L4_SM estimates are further used to estimate the global carbon budget (L. A. Jones et al., 2017) making the SMAP L4 one of only a few linked terrestrial land surface-carbon cycle reanalyzes (see also Section 2.5).

Recently, Naz et al. (2020) provided a 16 years (2000–2015) high resolution (3 km) European Surface Soil Moisture ReAnalysis (ESSMRA). An important aspect is the scaling of coarse observations by the data assimilation system with benefits also for the whole soil moisture profile and runoff simulation (Naz et al., 2020). The assimilation system uses the Ensemble Kalman Filter assimilating coarse resolution (25 km) remotely sensed ESA CCI soil moisture (Gruber et al., 2019; Wagner et al., 2012) into the community land model CLM version 3.5 (Oleson et al., 2008) for generating a 20 member ensemble of soil moisture states. The land surface model used to build the reanalysis is forced with the regional high resolution atmospheric reanalysis COSMO-REA6 (Bollmeyer et al., 2015) and annually variable leaf area index.

Multiple recent studies evaluated and compared land surface and soil moisture reanalysis products, indicating substantial error and therefore recommending great care in using land surface reanalysis products (Rotzer et al., 2015; Ullah et al., 2018). Temporal dynamics are often well represented comparing land surface reanalysis with satellite retrieved soil moisture and in-situ observations. Although temporal dynamics are well represented, absolute values rarely match across reanalysis products (Rotzer et al., 2015). Using soil moisture data from a reanalysis product and ground stations, Deng et al. (2020) reported that changes in soil moisture throughout the karst region of China and its subareas were mainly affected by precipitation, followed by temperature. In summary, climate, vegetation, and geological background determined the spatiotemporal distribution of soil moisture. The study found that the soil drying trend in recent decades and global climate change are not conducive to the ecological restoration of vulnerable karst areas. Y. W. Wang et al. (2021) conducted a global assessment of two blended microwave soil moisture products using in-situ measurements from the International Soil Moisture Network. The results indicated that the product from the Climate Change Initiative of the European Space Agency reveals overall better accuracy than that of the Soil Moisture Operational Product System from the National Oceanic and Atmospheric Administration. Ullah et al. (2018) reported significant errors in the soil moisture of reanalysis products particularly for freezing-thawing conditions given identical data input and different land surface models. Frequently, land surface reanalysis products are also compared in hydrologic studies (e.g., Ndehedehe et al., 2018) and to in-situ and remote sensing observations (e.g., Albergel et al., 2013; Kumar et al., 2019; Su et al., 2018). We note that the update of biogeochemical soil and vegetation states, plant phenology and parameters were not considered in these land surface reanalyzes. Carbon cycle reanalysis allows for resolution of biogeochemical processes beyond climatology parameterization. Terrestrial hydrologic reanalysis enhances the resolution of the terrestrial water cycle using enhanced horizontal connectivity and additional data sources.

Table 2
Models Potentially Suitable for Terrestrial Ecosystem Reanalysis, Key Processes and Parameterization Modes

Land surface and ecosystem model	Land cover/ vegetation Classes	Surface representation	Soil temperature	Canopy hydrology	Soil hydrology
CARDAMOM-DALEC		One canopy layer, and three soil layers	N/A	interception, throughfall and drip	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil
CHTESSEL	20	Two vegetation layer, 4 soil layers, 1 snow layer	Heat transfer in soil and snow	interception, throughfall and drip	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil
CLM (3.5)	17	One vegetation layer, 10 soil layers, 5 snow layers	Heat transfer in soil and snow	interception, throughfall and drip	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil, 1-D groundwater
CLM(5.0)	16	One vegetation layer, 25 soil layers, 10 snow layers	Heat transfer in soil and snow	interception, throughfall and drip	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil, 1-D groundwater
CLM-PF	17	One vegetation layer, 10 soil layers, 5 snow layers	Heat transfer in soil and snow	interception, throughfall and drip	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil, 3-D groundwater
HTESSEL	20	Two vegetation layer, 4 soil layers, 1 snow layer	Heat transfer in soil and snow	interception, throughfall and drip	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil
ISBA		One vegetation layer, 2–14 soil layers, 12 snow layers	Heat transfer in soil and snow	interception, throughfall and drip	Forece-store
JULES	9	Multiple canopy layers, 4 soil layers, multiple snow layers		interception, throughfall and drip	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil, lower boundary no-flux condition
LPJ-Guess	10	Two vegetation layer, 2 soil layers, no snow layer	No heat transfer	No	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil
mHM	3-16[a]	6 soil layers; 1 snow layer	Energy balance approximation;	interception, throughfall and drip	surface runoff, infiltration, subsurface runoff contributions (saturation excess), groundwater reservoir[b]
Noah-MP	17	One canopy layer, three snow layers, and four soil layers	Heat transfer in soil and snow	canopy interception loss, and transpiration, uniformly distributed roots and varying root depths	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil, 1-D groundwater
VIC	12	Two vegetation layer, 3 soil layers, 2 snow layers	Heat transfer in soil and snow	interception, throughfall and drip	Surface runoff, infiltration, sub-surface drainage, redistribution of water within soil

Abbreviations: CARDAMOM, Carbon Data Model Framework; HTESSEL, Hydrology-Tiled ECMWF Scheme for Surface Exchanges over Land; ISBA, Interactions Soil Biosphere Atmosphere; VIC, Variable Infiltration Capacity model.

[a]Depends on the data sets available. [b]Detail groundwater coupled with OpenGeoSys. [c]Land cover dynamically affect model parameters via MPR upscaling (Samaniego et al., 2010).

[d]Via MPR for all input geophysical data (soil properties, DEM, etc) and all parameters. Some processes are also represented at multiple scales.

Runoff routing	Carbon cycle	Land cover change	Snow hydrology	Subgrid variability	Scale	Grid structure	Reference
no	Yes (4 plant pools, 2 dead organic matter pools)	From satellite data	No	Variable resolution grid	global/ regional	regular grid	Bloom et al. 2016
no	Yes	Static	Snow accumulation and melt, compaction and water transfer between snow layers		global/ regional	regular grid	Boussetta et al. 2013, JGR
yes	No	Static	Snow accumulation and melt, compaction and water transfer between snow layers	Subgrid PTFs	global/ regional	regular/irregular grid	Oleson et al. 2007
yes	Photosynthesis, litter C, SOC, decomposition, plant respiration, and disturbance (fire)	Dynamic	Snow accumulation and melt, compaction and water transfer between snow layers	Subgrid PTFs, runoff	global/ regional	regular/irregular grid	Lawrence et al. 2019
yes	No	Static	Snow accumulation and melt, compaction and water transfer between snow layers	Subgrid PTFs	regional	regular/irregular grid	Maxwell and Kollet 2008
No	no	Static	Snow accumulation and melt, compaction and water transfer between snow layers		global/ regional	regular grid	Balsamo et al. 2009, JHM
No	yes	Static	Snow accumulation and melt, compaction and water transfer between snow layers	Subgrid runoff	global/ regional	regular grid	Noilhan and Mahfouf 1996, GPC
yes	yes	Yes	zero-layer model and multi-layer snow	Subgrid PTFs	global/ regional	regular grid	Best et al. 2011
No	Photosynthesis, litter C, SOC, decomposition, plant respiration, and disturbance (fire)	Dynamic	No		global/ regional	regular grid	Smith et al. (2001)
multiscale river routing + lake modeling	no	dynamic[c]	snow accumulation and melting	yes[d]	global/ regional	regular/irregular grid	Samaniego et al. 2010
No	yes (plant: 3 pools: leaf, wood, and root) and two soil carbon pools (fast and slow).	Static	liquid water storage in snow, snow-interception model, melt/refreeze capability, sublimation of canopy-intercepted snow	semi-tile vegetation and bare soil	global/ regional	regular grid	Niu et al. 2011
yes	No	Static	Snow accumulation and melt, compaction and water transfer between snow layers		global/ regional	regular grid	Liang et al. 1994

2.4. Hydrological Reanalysis

A large number of studies have attempted to quantify aspects of the Earth's hydrological cycle through the combination of multiple data sources by using either data assimilation (which can be considered reanalyzes) or statistical model-data fusion approaches which cannot be considered reanalyzes in the strict sense but we believe are also of interest to the readership. Here, we provide a brief overview of key (quasi-)global studies focusing on the overall water budget (Pan et al., 2012; Rodell et al., 2015; Sahoo et al., 2011; Zhang et al., 2018) or on specific hydrological components, including evapotranspiration (Hobeichi et al., 2018; Jimenez et al., 2018), runoff (E. A. Clark et al., 2015; Ghiggi et al., 2019; Hobeichi et al., 2019), and terrestrial water storage (Humphrey & Gudmundsson, 2019; van Dijk et al., 2014).

Among the four studies focusing on the overall water budget, two used data assimilation to blend multiple data sources (Pan et al., 2012; Zhang et al., 2018), Sahoo et al. (2011) used weighted averaging with the Constrained Ensemble Kalman Filter (CenKF) to close the water balance component, while Rodell et al. (2015) used simple (unweighted) water balance averaging. The two earliest studies (Pan et al., 2012; Sahoo et al., 2011) performed their analyses using catchment averages, Rodell et al. (2015) used continental averages, whereas Zhang et al. (2018) used 0.5°-resolution gridded averages. Sahoo et al. (2011) relied primarily on satellite-based sources for quantifying the four main components of the water budget (precipitation, evapotranspiration, runoff, and terrestrial water storage) for 10 major river catchments globally for a four-year period (2003–2006). They found that closure was generally not possible, with errors ranging from 5% to 25% of mean annual precipitation. Pan et al. (2012) considered the same four components, but analyzed a longer period (1984–2006) and also considered in-situ- and model-based data sources. They focused on 32 major catchments across the globe, and concluded that the assumptions underpinning the error analysis may not hold for all regions. Rodell et al. (2015) focused on the entire globe and analyzed the atmospheric water budget in addition to the surface water budget for the period 2000–2010. They found that closure within 10% was generally possible. Zhang et al. (2018) analyzed the entire land surface for the period 1984–2010 and reported that the main challenge was the sparseness and limited availability of "ground truth" observations for bias correction of the individual components.

The two studies focusing on evapotranspiration (Hobeichi et al., 2018; Jimenez et al., 2018) used FLUXNET observations (http://fluxnet.fluxdata.org/) as reference to derive merged gridded estimates for the land surface at 0.5° resolution for 2000–2009 and at 0.25° resolution for 2002–2007, respectively. Arguably the main challenge in these studies is the fact that evapotranspiration is a largely invisible process that is, highly variable in space and time and therefore difficult to measure. The three studies focusing on runoff (E. A. Clark et al., 2015; Ghiggi et al., 2019; Hobeichi et al., 2019) all used streamflow observations from the Global Runoff Data Center (GRDC) as reference to derive 0.5°-resolution merged gridded estimates using bias-correction for 1950–2008, optimal weighting for 1980–2012, and random forest regression for 1902–2014, respectively. Major obstacles to derive merged gridded runoff estimates are the scale discrepancy between local runoff from individual hillslopes and streamflow from large catchments and the fact that the majority of the globe is ungauged or poorly gauged. The two studies focusing on terrestrial water storage (Humphrey & Gudmundsson, 2019; van Dijk et al., 2014) both used gravity anomaly measurements from the GRACE satellite-pair to obtain gridded terrestrial water storage estimates for 2003–2012 using data assimilation and for 1901–2014 using a statistical approach, respectively. A limitation of GRACE is the lack of fine spatial detail due to GRACE's large footprint size (∼400 km).

Hydrologic connectivity in lateral and vertical direction are key processes in these reanalyzes. Vertical oriented grid based land surface models used for land surface reanalysis often limit lateral flow, ponding and infiltration process representation (Vereecken et al., 2019). Distributed hydrological models integrate surface-subsurface water interaction across nodes and grid cells by solving large systems of partial differential equations including lateral water fluxes, infiltration, unsaturated, surface, and groundwater flow. The Interactions Soil Biosphere Atmosphere (ISBA-SURFEX) model (Decharme & Douville, 2006; Noilhan & Mahfouf, 1996), ParFlow-CLM (Kollet & Maxwell, 2008), and the Catchment Land Surface Model (Catchment LSM) are examples of such distributed or semi-distributed hydrologic models. However, a resolution of above 25 km grid size, model setup (e.g., climatology) and limited data availability undermine the assumptions for three-dimensional water flow process representation in support of one-dimensional vertical water

flow process representation with limited grid cell inter-action. Spatial resolution is also a key challenge for dynamic vegetation, nutrient and carbon cycle modeling in terrestrial carbon cycle reanalysis.

2.5. Terrestrial Carbon Cycle Reanalysis

This section discusses terrestrial carbon cycle models and their incorporation into carbon cycle reanalysis. Terrestrial carbon cycle models include a detailed representation of land surface biogeochemistry, targeted at carbon cycling in plants, and soils (e.g., photosynthesis and respiration), with a model-dependent element of feedback between the C cycle and climate, water and N cycles. Models vary in their complexity, and can include carbon allocation, leaf phenology, impacts of biomass burning and wildfires, disturbance and succession, land use and land cover change. Vegetation in these models is commonly represented and parameterized by plant functional types. These are groupings of species with similar life forms (e.g., grasses, trees) that show a similar response to a given set of environmental conditions (e.g., tropical, boreal). Terrestrial carbon models rely on meteorological reanalysis data like precipitation, air temperature, shortwave radiation and vapor pressure deficit as model driving inputs for regional to global applications.

The key processes in carbon cycle models have been studied at various scales by networks of eddy covariance measurements (i.e., FLUXNET, Papale et al., 2006; Reichstein et al., 2007), field experiments (Chabbi et al., 2017; Grosse et al., 2020) and ecosystem manipulations simulating for example, atmospheric carbon dioxide enrichment (Ainsworth & Long, 2005; Wieder et al., 2019). However, the terrestrial carbon cycle remains poorly constrained, with uncertain interactions and feedbacks (e.g., Friedlingstein et al., 2014; Huntzinger et al., 2017). This is largely because terrestrial carbon models rely on these *in situ* observational data for model parameterization and verification. Data time series are relatively short, and data are especially scarce from the tropical, arctic, and boreal regions compared to other regions. However, advances in satellite observation platforms, combined with new and existing *in situ* data, provide an opportunity to combine these data with terrestrial carbon models using, for example, data assimilation, for a better understanding of the carbon cycle in these regions and elsewhere (Schimel et al., 2015; Scholze et al., 2017).

Pioneering work was done in the 1990s by Knorr and Heimann (1995) using the Simple Diagnostics Biosphere Model coupled at a 0.5° resolution with a 7.83° × 10.0° atmospheric tracer circulation model. The atmosphere-biosphere interaction was constrained using FAPAR remote sensing and sparse in-situ CO_2 observations at five sites over the period of 2 years. Since then reanalyzes of the terrestrial carbon cycle have been produced with a broad range of approaches and increased their resolution and data inputs. The objective of these reanalyzes has been to inform process-based carbon modeling using measurements for calibration, to provide a better estimate of the terrestrial carbon cycle. While the history, methodology, and models used in carbon cycle data assimilation systems are extensively discussed in Scholze et al. (2017), we include key highlights below:

The land component of the Carbon Cycle Data Assimilation System project (CCDAS) was initially built around the Jena Scheme for Biosphere Atmosphere Coupling in Hamburg (Raddatz et al., 2007; Scholze et al., 2017), followed by Biosphere Energy-Transfer Hydrology (BETHY, Knorr, 2000) model with the objective to provide a reanalysis for carbon fluxes (Kaminski et al., 2012). Within CCDAS, FAPAR data, eddy flux data (Baldocchi et al., 2001), and remotely sensed soil moisture data are assimilated, leading to reduced land surface flux uncertainty. The CCDAS assimilation approach uses an adjoint method, whereby a tangent linear version of the model code is generated through automatic differentiation. From this adjoint, parameters can be optimized to the data input.

The CCDAS framework was more recently used with the ORCHIDEE land surface model to generate a carbon reanalysis set for the years 2000–2009 (Peylin et al., 2016). This product assimilated FLUXNET observations, atmospheric CO_2 emissions and the Normalized Difference Vegetation Index (NDVI) monitored from the Moderate Resolution Imaging Spectrometer (MODIS) as a proxy for plant phenology, which significantly constrained the growing season. The CCDAS framework has also been applied to assimilate new satellite-derived measurements of solar induced fluorescence to constrain monthly and daily simulated carbon fluxes and parameter values (Koffi et al., 2015), replacing the BETHY model photosynthesis schemes with those from SCOPE (Soil Canopy Observation, Photochemistry, and Energy fluxes), which also includes a fluorescence model (van der Tol et al., 2009).

A recent CCDAS study of Castro-Morales et al. (2019) simulated three decades of global terrestrial carbon fluxes by assimilating data with different periods of observations to evaluate the ability of a carbon cycle reanalysis to predict long-term trends and variability in the global carbon cycle. Here, the data assimilation framework was built upon the JSBACH land surface model (Dalmonech & Zaehle, 2013; Raddatz et al., 2007; Reick et al., 2013) and is called the Max Planck Institute MPI-CCDAS. This framework uses the methodology of Kaminski et al. (2012) that simultaneously reduces the model–data mismatch for multiple independent carbon cycle data sets. Castro-Morales et al. (2019) find MPI-CCDAS is capable of simultaneously integrating two independent observational data sets, the fraction of absorbed photosynthetic active radiation (FAPAR) and atmospheric CO2 concentrations, over three consecutive decades at the global scale to estimate global terrestrial carbon fluxes. MPI-CCDAS can confidently predict carbon fluxes up to five years, with reduced certainty for long-term forecasts.

The Carbon Data Model Framework (CARDAMOM, Bloom & Williams, 2015), uses a different approach to data assimilation, that avoids the need for an adjoint. CARDAMOM uses Monte Carlo methods, where large ensembles of the selected model are simulated and evaluated against observations. Bayesian methods are used to accept or reject parameters such that a set of parameters consistent with data and data errors are identified. Because millions of model runs are required to find robust solutions, the model must be fast running, and therefore of intermediate complexity, for example, DALEC (M. Williams et al., 2005). CARDAMOM also makes use of ecological and dynamic constraints to simplify the search for realistic parameters (Bloom & Williams, 2015). CARDAMOM has been used globally to assimilate biomass and soil maps and time series of LAI data to assess plant carbon allocation, stocks, residence time, and carbon use efficiency. Because CARDAMOM avoids the specification of plant functional types, parameter maps are emergent from the DA process pixel by pixel across the model domain. As a result, a key finding from CARDAMOM is that land cover types used by typical Earth System Models do not adequately depict the spatial variability of carbon cycle parameters and processes (Bloom et al., 2016). CARDAMOM has been used to estimate the global terrestrial carbon cycle for the first 10 years of the 21st Century, identifying biome and continental variations in carbon residence times (Bloom et al., 2016) that are critical determinants of C-climate sensitivity in model forecasts.

Although with currently a relatively short time span starting in March 2015, the SMAP Level-4 Carbon product is an interesting candidate for a carbon-related reanalysis. It is driven by surface meteorological forcing data from the Goddard Earth Observing System (GEOS), the SMAP L4_SM (R. Reichle et al., 2016; R. H. Reichle et al., 2019), and Moderate Resolution Imaging Spectroradiometer (MODIS) satellite observations (land cover classification and 8-days canopy FPAR). From the CASA and CENTURY models the simplified light use-efficiency plant production and soil organic matter decomposition logic have been implemented, relating the carbon cycle components to basic meteorological conditions and vegetation-ecosystem functional characteristics (L. A. Jones et al., 2017). The global results are provided at 9 km and daily resolutions, and inform about Net Ecosystem CO2 exchange (NEE) computed as total respiration (vegetation plus soil) less vegetation gross primary production (GPP). By improving the coupling between the water and carbon cycles, the SMAP Level-4 Carbon product may pave the way toward an integrative hydrology-carbon reanalysis.

Overall, these studies are promising in terms of leading to a better ability to understand the carbon sink strength of terrestrial ecosystems across the globe, while also emphasizing the importance of operational networks for *in situ* data and continuous effort. These studies improve the incorporation of the terrestrial carbon cycle dynamics to consider and quantify its feedbacks to the climate system (Heimann & Reichstein, 2008). There is a strong potential for future work to advance C cycle understanding, given the number of new satellite observations being prepared or planned. C cycle DA should aim to assimilate atmospheric CO_2 data (Schimel et al., 2015); direct observations of the C cycle from repeat biomass mapping (Quegan et al., 2019); high resolution and frequent sensing of canopy properties; photosynthesis inferred from solar induced fluorescence (Damm et al., 2010); burned area and land use change mapping (Hansen et al., 2010); soil and canopy moisture (van der Schalie et al., 2016) and evapotranspiration (Hulley et al., 2017).

2.6. Error Assessment for Reanalysis

A key challenge for any reanalysis is to have access to robust estimates of error associated with the satellite or other products that are assimilated. The error plays a key role in weighting the inversion process. If the weighting is incorrect then the reanalysis may be biased by products that are of lower quality than expected. To mitigate this risk requires close interaction with field scientists who can provide calibration data for the algorithms used to convert remote sensing or other data into ecological information. This calibration process can attach a clear estimate of systematic and random bias to the satellite product (e.g., see Ryan et al., 2012 for a biomass error characterization). While more satellite products now come with error statistics, independent evaluation indicates that these errors can be underestimated (Y. Zhao et al., 2020). A concerted effect to characterize error robustly is required for effect reanalysis.

3. Status of Model Data Fusion Methods in Reanalysis

Bayesian statistics, stochastic algorithms and ensemble simulation methods are frequently used to quantify the uncertainties in model-data-driven reanalyzes ranging from ocean sciences (Axell & Liu, 2016; Ciavatta et al., 2016; Schartau et al., 2010; Simon et al., 2015; J. P. Xie et al., 2017; Xue et al., 2012), atmospheric sciences (Candiani et al., 2013; Compo et al., 2011; Whitaker et al., 2004), to terrestrial ecosystem sciences (Dunne & Entekhabi, 2005; Montzka et al., 2012). The uncertainty of a reanalysis can be quantified and the magnitude of the uncertainty typically depends on observation uncertainty and influence, uncertainty of model inputs (e.g., atmospheric forcings), (uncertain) model dynamics, process representation, soil and vegetation parameter uncertainty, and parameters (Dietze, 2017; J. P. Xie et al., 2017). Reanalysis across various disciplines as described in Sections 2.1–2.5 is based on a variety of model-data fusion methods including variational data assimilation (3DVAR, 4DVAR, and hybrid 4DVAR), sequential data assimilation (various variants of the Kalman filter and the particle filter), smoothing and Markov Chain Monte Carlo methods (MCMC). These methods are discussed in more detail and with limited examples in the following sections. This section focusses more on the methodological aspects while examples for reanalyzes are provided in the reanalysis product Table 1.

3.1. Ensemble Kalman Filter

The Kalman filter was originally developed for linear systems (Kalman, 1960). The key of the Kalman filter is the dynamic propagation of the prior estimate errors by a prognostic model. Because ecosystem models and remote sensing observation models are non-linear, and because the prognostic state vector can be large, the ensemble Kalman filter (EnKF) was proposed (Burgers et al., 1998; Evensen, 2003; R. H. Reichle et al., 2002) to diagnose the state error covariance matrix recursively from a sample ensemble of realizations. The Ensemble Kalman Filter is frequently used to generate atmospheric (Compo et al., 2011; Slivinski et al., 2019), oceanic (Ciavatta et al., 2019), and terrestrial reanalyzes (Naz et al., 2020; R. H. Reichle et al., 2019). An ensemble of model forecasts is generated by perturbing model input, state variables and/or parameters. These forecasts are compared to observations, when available. Based on the relative ensemble-based uncertainty in the forecasts and the observations, the ensemble model trajectories are updated and used as initial conditions to subsequent forecasts. The EnKF is directly applicable to estimate unobserved variables, for example, to estimate root-zone soil moisture from observed brightness temperature, to inter- and extrapolate information from one region to another (R. H. Reichle et al., 2014), or to downscale data via spatial filtering. The EnKF is also used for the joint estimation of model states and unknown parameters (Y. Chen & Zhang, 2006). The EnKF is one of the most popular techniques for sequential data assimilation in non-linear systems for its ease of implementation, but it also has shortcomings. In case of a larger state vector, the ensemble size needs to increase; the choice of the perturbation parameters will determine the optimality of the filter; covariance inflation may be needed to keep sufficient ensemble spread, and state variables are assumed to follow a Gaussian distribution, among others. Important assumptions to the EnKF and other filters are prior knowledge about observation and process error covariance matrices. Recent developments include efficient EnKF-variants which compress state space, and improving the performance of EnKF by extending the data assimilation window, and the use of an iterative approach, which gives rise to iterative ensemble smoothers (Bocquet & Sakov, 2014; Emerick & Reynolds, 2013; Evensen, 2018). Also the generalization of the EnKF method toward new assimilation algorithms is a recent development which

enables ecosystem models and assimilation of non-Gaussian data (Raiho et al., 2020). Many studies have focused on the sequential assimilation of soil moisture data (M. L. Carrera et al., 2015; De Lannoy & Reichle, 2016; de Rosnay et al., 2013; Draper et al., 2012; R. H. Reichle, De Lannoy, et al., 2017) and snow (De Lannoy et al., 2010; Kumar et al., 2017; Thirel et al., 2013; Toure et al., 2018). M. Williams et al. (2005) used EnKF to integrate both flux data and biometrics (stock data) in a model analysis of a forest carbon cycle. Smoothing has also been used for soil moisture (Dunne & Entekhabi, 2005), to reconstruct snow (Durand et al., 2008) or to infer snow and soil and deep groundwater estimates from GRACE measurements (Girotto et al., 2016; Kumar et al., 2016; Zaitchik et al., 2008).

3.2. Particle Filter

A particle filter is essentially a sequential Monte Carlo method that approximates the probability density function of the posterior states by a set of random samples. Compared to the EnKF, the particle filter has the advantage that it can correctly process uncertainties that follow any non-Gaussian distribution. In particle filtering, the probability density function of the posterior state vector is approximated by a set of random samples. These are labeled particles, each of which has its own weight. A first step in the application of the particle filter is Sequential Importance Sampling (SIS), in which each of the weights are updated using the external observations. Due to the use of a sub-optimal approximation of Bayes' rule, the variance of the weights tends to increase, leading to a large number of particles with small importance weights. For this reason, Sequential Importance Resampling (SIR) needs to be applied. In this step, particles with a high importance are retained, and their values are assigned to the state vectors of particles with low weights. The weights of the new set of particles are then all set equal. One problem that may arise is particle degeneration, in which the particle set collapses to a single particle. This can be solved through the resample-move step, in which Monte Carlo Markov Chains are applied to the particle set. For a more detailed description of the Particle Filter we refer to Doucet et al. (2000). Recent developments in particle filtering are more promising for their application in high dimensional systems, and therefore also for a possible future role in reanalyzes. Examples are the variational mapping particle filter (Pulido & van Leeuwen, 2019) and localized particle filter (Penny & Miyoshi, 2016; Poterjoy, 2016). Studies focusing on the application of the particle filter in ecological sciences can be found in (Dowd & Joy, 2011; Knape & de Valpine, 2012; Martin-Fernandez et al., 2014; Rakhimberdiev et al., 2015; Weir et al., 2013). For ecosystem reanalysis we can expect that many states and parameters will show non-Gaussian distributions, so that Kalman-type assimilation algorithms perform suboptimal. Efficient particle filters are therefore an interesting future alternative for ecosystem reanalysis, but currently not efficient enough and not well established for reanalyzes.

3.3. Variational Data Assimilation: 3DVAR and 4DVAR

Variational data assimilation is based on a Gaussian approximation of Bayes law, weighting simulation model-data mismatches on one hand (the likelihood term) and mismatches between updated model variables and prior model variables on the other hand (referred to as the background part in atmospheric sciences). This results typically in a two part objective function which can be minimized making use of adjoint state techniques in combination with non-linear optimization (Compo et al., 2011). In Earth sciences, either 3D variational data assimilation (3DVAR) or 4D variational data assimilation (4DVAR) is used. In 4DVAR, the minimization is carried out over a longer time window taking into account that measurements which are used for assimilation are made at different time points. 4DVAR is commonly used in combination with atmospheric models (e.g., see Kalnay, 2003 for an overview), and also in groundwater hydrology (e.g., J. Carrera & Neuman, 1986; Gomez-Hernandez et al., 1997). For land surface data assimilation with a focus on the carbon cycle, 4DVAR is used in combination with the ORCHIDEE-model (Peylin et al., 2016). New methodological developments include the estimation of the background error covariances through calculating the spread of the ensemble in hybrid 4DVAR methods. In hybrid 4DVAR the background error covariance matrix is combined from a prior, static covariance matrix and a covariance matrix from an ensemble. Ensemble 4DVAR methods are based on an ensemble of trajectories so that the use of linear and tangent models at each iteration is avoided, and the model error covariance matrix is calculated from the ensemble (Lorenc et al., 2015). Variational data assimilation is also of high interest for ecosystem reanalysis, as we are dealing in ecosystem reanalysis with processes which act on very different time scales, and many unknown

parameters which are also linked to these disparate time scales. Minimization of an objective function over a larger time window can potentially take better account of these different time scales than sequential data assimilation.

3.4. Markov Chain Monte Carlo (MCMC)

Markov-Chain Monte-Carlo is a batch method for state and parameter estimation. MCMC solves general inverse problems through determining the probability distribution of a vector of model parameters given a set of measurements (Knorr & Kattge, 2005). The initial approach was developed by Metropolis et al. (1953) to directly sample the parameter probability distribution using Monte Carlo techniques. The complete method of Monte Carlo inversion is described in detail by Mosegaard and Tarantola (1995) and reviewed by Mosegaard and Sambridge (2002). The Metropolis algorithm operates by updating prior information on parameters (expected values or ranges) with a model-observation comparison, to guide a Markov chain (random walk) through parameter space and has been adopted by Vrugt et al. (2013). The algorithm is a batch process, so for each proposed parameter step a complete run of the model is required. Multiple chains, each typically with millions of members, are required to test for consistency in final likelihoods, using convergence tests. The REFLEX experiment (A. Fox et al., 2009) explored the efficacy of varied different data assimilation techniques, including Kalman filters and batch methods like MCMC to analyze carbon flux data. Bloom et al. (2016) used the adaptive Metropolis MCMC approach in combination with a simplified ecological model to produce a reanalysis of the terrestrial carbon cycle. Overall MCMC can have high computational costs due to the large number of simulations required, but unlike the EnKF, MCMC preserves any mass balance imposed by the model (Hill et al., 2012). The MCMC method is not yet efficient enough for large scale ecosystem reanalyzes, but its use in an ecosystem reanalysis could be the estimation of vegetation trait specific parameters at highly equipped sites, which are used at other sites (grid cells) with the same vegetation type.

3.5. Software Tools Available for Model Data Fusion

State data assimilation can start simple–the classic Kalman Filter can be implemented in a few lines of code for the scalar case -, but implementation can quickly become more complicated when using more advanced methods that relax simplifying assumptions or deal with large spatial extents or data volumes. On top of this is the informatics hurdle of processing model inputs, starting and stopping ensembles of model runs, and ingesting data constraints, which can quickly spiral out of control. By contrast, well-designed software frameworks can generalize and abstract many of these steps, allowing data assimilation systems to scale more easily. Utilizing community-supported tools can also be more robust, as a larger development community has played a role in testing code, and more efficient, as it results in less duplicated efforts and shallower learning curves (Fer et al., 2020).

Fortunately, when it comes to the state data assimilation approaches used in reanalysis and iterative forecasting, there are a number of alternative frameworks available. One of the most established is the Data Assimilation Research Testbed (DART, https://www.image.ucar.edu/DAReS/DART/) maintained by the U.S.'s National Center for Atmospheric Research (NCAR). DART supports a number of different ensemble-based DA algorithms (Anderson et al., 2009), with a focus on the Ensemble Adjustment Kalman Filter (EAKF), a variant of EnKF that nudges ensemble members. In terms of ecosystem applications, A. M. Fox et al. (2018) coupled DART to NCAR's Community Land Model (CLM4.5) and demonstrated its ability to assimilate both real and simulated biomass and leaf area data at the site-level using observations from an Ameriflux site in New Mexico. In this application ensemble spread was generated based on state and driver uncertainty, and parameters were held constant. Viskari et al. (2015) also coupled DART to the Ecosystem Demography model (ED2, Medvigy et al., 2009) to assimilate both tower-based and remotely sensed (MODIS) phenological observations. Similar to DART, the German Alfred-Wegener-Institute maintains the Parallel Data Assimilation Framework (PDAF, http://pdaf.awi.de/), which similarly supports multiple ensemble-based algorithms (Nerger & Hiller, 2013). Kurtz et al. (2016) coupled PDAF to the terrestrial systems modeling platform (P. Shrestha et al., 2014) achieving a very favorable scalability related to the fact that all data assimilation steps can be performed via memory, also for very large problems. This coupling allows

applications for land surface and subsurface models. PDAF was also coupled to oceanic models (Nerger et al., 2006), and more recently atmospheric models.

In contrast to DART and PDAF, which are focused solely on data assimilation, data assimilation utilities also exist within more general model-data informatics systems, such as PEcAn (http://pecanproject.org Dietze et al., 2013; Lebauer et al., 2013). As of writing PEcAn has been coupled to almost 20 ecosystem models, and four of those models (ED2, LINKAGES, SIPNET, and LPJ-GUESS) have implemented the additional modules required to use data assimilation. PEcAn also supports a more generalized ensemble filter based on a multivariate Tobit data model, which is an alternative distribution to the Gaussian and better accommodates zero-bound, proportion, and zero-inflated observations, and a Wishart process error model in place of the traditional assumption that the model's process error is known (Raiho et al., 2020). PEcAn also handles a number of other aspects on top of a data assimilation framework such as job tracking or archiving, input processing, data ingest, and visualization, and can quantify and propagate additional uncertainties, such as parameter uncertainty, parameter variability (random effects), driver uncertainty, and process error.

3.6. Computational and Big Data Aspects

The generation of reanalysis products as described in Section 2 and the reanalysis specific algorithmic procedures presented in Sub-Sections 3.1–3.7 are demanding computationally as well as in terms of data volume and data variety. We encourage readers to embrace the technical, computational and big data processing aspects. In the following paragraphs, we review the diverse solutions developed on high performance computers for simulating real world problems and for producing Earth system reanalysis. The examples demonstrate the technical challenges addressed in past, present and future reanalysis.

The evolution of reanalyzes is in line with overall developments in geoscience modeling, which see increases in model's spatial resolution (Prein et al., 2015; Stevens et al., 2019) with simultaneously expanding model domains of regional high-resolution models (Leutwyler et al., 2016), multi-physics fully coupled Earth system models (Eyring et al., 2016; Giorgi & Xue-Jie, 2018; R. R. Shrestha et al., 2014), and many ensemble members in climate change experiments (Eyring et al., 2016) and data assimilation studies (Kurtz et al., 2016; Naz et al., 2020). For example, the 16-years pan-European 3 km soil moisture reanalysis in Naz et al. (2020) with the coupled CLM-PDAF model-data assimilation system and 20 ensemble members accounts for a manageable 100k CPU core hours using 1920 CPU cores simultaneously per data assimilation experiment on a standard Linux cluster with about 7.4 simulated years per day (SYPD) wall clock time. SYPD measures the number of simulated years per 24h wall clock time on any given computational platform. The ERA5 reanalysis (Hersbach et al., 2020) as an example of a global atmospheric reanalysis accounts for a computationally more expensive 0.016–0.025 SYPD. Splitting the simulation time into a number of concurrently running, independent simulation streams makes the computational problem more manageable (Hersbach et al., 2020).

These developments are enabled by steady HPC developments toward massively parallel, heterogeneous (e.g., CPUs and GPUs combined), modular peta-scale supercomputers, providing ever-increasing computational resources (Davis et al., 2012; Dongarra et al., 2018; Schulthess et al., 2019) while making resource efficient simulations on the latest HPC systems technically demanding (Fuhrer et al., 2018). Hence, Earth system models (ESMs) and accompanying software tools have evolved into sophisticated, complex applications (P. Bauer et al., 2015). To make efficient use of today's pre-exascale (GPU-accelerated) HPC systems, performance-portable, highly scalable simulations, processing, analysis and visualization applications and workflows are in constant development (Schulthess et al., 2019). Developments include co-design approaches that combine hardware with software frameworks and algorithmic developments for example, by using domain-specific languages (DSLs; Lawrence et al., 2018), or by increasing memory use efficiency (Fuhrer et al., 2018). This usually requires a refactoring and substantial code modernizations of legacy models (Fuhrer et al., 2018), data processing chains and storage concepts.

Coupled multi-physics Earth system models link the Earth's compartments through mass, energy, momentum transfers and the biogeochemical cycles across multiple spatio-temporal scales and thereby improve the realism of key processes in the Earth system (Eyring et al., 2016; Giorgi & Xue-Jie, 2018; Heinze et al., 2019). Technically, one distinguishes external and internal two-way coupling. Common to all coupling solutions

is to strive for modularity, flexibility, and portability of the implementation (Valcke et al., 2012). External couplers such as OASIS3-MCT (Valcke, 2013) or YAC (Hanke et al., 2016), provide a synchronized exchange of information along compartmental interfaces. For external coupling, computations, transformations and communications are usually done concurrently with parallelized codes and in memory (online coupling) to allow scalability of coupled systems. Internal coupling is a more code-intrusive approach which can also be combined with external coupling. Examples of the internal coupling approaches are the Earth System Modeling Framework (ESMF; Collins et al., 2005) or the Modular Earth Submodel System (MESSy; Jockel et al., 2010), that couples unified component submodels that allow for a process based coupling, irrespective of compartmental interfaces (e.g., in atmospheric chemistry). Typical challenges in coupling are load balancing between different component models, which heavily affects the overall performance and thereby also the scaling of the application (Gasper et al., 2014; Valcke, 2013), and the establishment of common software infrastructures with standardized interfaces for purpose-built and generic couplers. Another emerging challenge is the efficient use of modular, heterogeneous supercomputers by multi-component coupled models that, for example, offload certain components on different hardware partitions.

The model and HPC developments, inevitably lead to big data challenges (De Mauro et al., 2016; Kitchin & McArdle, 2016; Overpeck et al., 2011). This is mainly due to the unprecedented data volumes throughout the data lifecycle, affecting data generation, transfers, storage, analysis, dissemination, and archival (Gandomi & Haider, 2015; Overpeck et al., 2011; Schnase et al., 2016). The data volume increase is mainly due to a higher spatio-temporal resolution, shorter output intervals, ensemble runs and more variables. In case of the transition from the global ERA-Interim to the ERA5 reanalysis (See Section 2) horizontal resolution changes from 79 to 31 km, vertical resolution from 60 to 137 levels and temporal resolution from 6- or 3-h to 1-h output intervals with more even variables (Dee et al., 2011; Hersbach et al., 2020), resulting in about 5 petabytes total data volume for ERA5 (Hersbach et al., 2020). Going from ERA-Interim to ERA5 leads, for example, to a factor 80 data volume increase at full resolution in a Lagrangian transport simulation study by (Hoffmann et al., 2019), while there are calls for exascale climate modeling at 1 km global resolution (Palmer, 2016). The simulation, even with massively parallel model systems and parallel data assimilation frameworks, may become memory-limited, depending on the data assimilation algorithm in combination with the ensemble size and resolution (Section 3).

Transitioning toward a full representation of the Earth's water and energy cycles, more input observations from a large number of data sources (radiosonde, aircraft, satellite, soundings, etc.) are used with the generation of a reanalysis, for example, from ERA-40 (S. M. Uppala et al., 2005) to ERA-Interim (Dee et al., 2011), and lately to ERA5 (Hersbach et al., 2020), data variet. also becomes an issue in the data pre-processing for the analysis. Aside from using parallel input and output from and to losslessly compressed, portable data formats, such as netCDF, energy- and time-consuming movements of simulation data can be minimized and the overall data volume reduced by in situ processing, which performs data analysis and visualization in memory (Ayachit et al., 2016; A. C. Bauer et al., 2016; Childs et al., 2019). As this is not always feasible or desirable, big data-capable processing and analysis, that is, doing concurrent computations using shared and distributed memory parallel computing paradigms on heterogeneous HPC systems with generic methods, also become increasingly available (e.g., Krajsek et al., 2018). Finally, as the simulation data has to meet FAIR (Findable, Accessible, Interoperable, and Reusable) principles (M. D. Wilkinson et al., 2016), research data management systems encompass the curation, analysis, publication, re-use, and archival components of the data life cycle. Prominent examples of federated data repositories that provide interoperable (e.g., standardized formats, common meta data conventions, controlled vocabularies, and data reference syntax), provenance-enabled (e.g., unique object identifiers) ECMWF reanalysis and CMIP climate model data in the multi-PB range are the Copernicus Climate Data Store (Buontempo et al., 2020; Hersbach et al., 2020), or the Earth System Grid Federation (ESGF; Cinquini et al., 2014; D. N. Williams et al., 2009), whose infrastructure can be seamlessly integrated via APIs into user workflows.

4. Toward Terrestrial Ecosystem Reanalysis

Several important ecosystem processes (photosynthesis, evapotranspiration, surface, or groundwater flow) and variables (carbon fluxes, gross primary production, soil moisture, soil temperature, and terrestrial water storage) are already considered in reanalysis studies of the land surface, hydrological processes or the

terrestrial carbon cycle. However, other important aspects (e.g., land use and land cover changes, disturbances, species migration) and variables (genetic composition, species traits, populations, ecosystem structure and functions and others) directly or indirectly related to the aforementioned are not considered in these reanalysis studies. Therefore, we argue to expand terrestrial ecosystem reanalysis beyond the previously discussed fields of application (land surface, hydrology, and terrestrial carbon cycle) by developing a framework that allows to develop a consistent set of products that take into account not only the underlying physical and chemical principles but also biochemical- and biological principles. Terrestrial ecosystem reanalysis will therefore enable better understanding, documentation and assessment of interactions and feedbacks between abiotic and biotic processes at different spatial and temporal scales but also the impacts of disturbances of various origin on the overall functioning of ecosystems and the services they provide. To develop a terrestrial ecosystem reanalysis framework, mathematical- and physical representation of theoretical processes in the form of models informed by both abiotic and biotic data and their interactions and coupling mechanisms are needed. Several recent concepts in ecosystem research provide the foundation for such terrestrial ecosystem reanalysis. These include: (a) integrated ecosystem models considering biotic-abiotic feedback mechanisms, (b) defining a consistent set of Essential Ecosystem Variables (EEV) as other scientific communities have identified them, (c) remote biotic and abiotic trait observations, (d) access to combined biotic and abiotic in-situ observations, and (e) access to specific biotic time series data. In the subsequent sections we briefly outline the elements.

4.1. Integrated Ecosystem Models

The challenge to predict and model especially biotic ecosystem variables is not new (Pereira et al., 2013; van den Hoogen et al., 2019). Global dynamic vegetation and land surface models incorporate important biogeophysical processes but lack representation of processes related to biotic variables (Table 2). In line with recent progress (Biber et al., 2020; van den Hoogen et al., 2020) we propose to develop models with stronger abiotic-biotic processes, their interactions and feedback mechanisms to produce meaningful continuous time series which go beyond biologic patterns. Species distribution models (SDMs) are the most common mathematical description in ecological modeling providing spatially explicit predictions based on regressions and/or complex and advanced machine learning models (Deep Learning, Bayes, Regression Trees, and others) in particular on presence-absence and abundance data (Elith & Leathwick, 2009; Jetz et al., 2019; Phillips et al., 2006). SDMs are often supported with predictors. Ecological predictors in the context of SDMs are ecosystem 2–4 D structural (slope, aspect, and altitude) and functional attributes (enhanced vegetation index, land surface temperature, and albedo), several climatic variables and spatially explicit landscape characteristics (Arenas-Castro et al., 2018) which are already output variables of terrestrial reanalysis. Stacked or joint SDMs combine correlative SDMs for multiple species (Biber et al., 2020; D. P. Wilkinson et al., 2019) while SDMs do not provide processes that lead to discovered patterns but infer these processes. There exist ecological process based models focusing on for example, physiology-related mechanisms (Connolly et al., 2017; Kearney & Porter, 2009), simulations on genetic architecture of phenotypes (Schiffers et al., 2014), ecological niche models (Regos et al., 2019), community dynamics, resource competition and biotic interactions (Staniczenko et al., 2017). A combination of all these approaches framed in a macro-ecologic or a macrosystem ecological modeling framework (Cabral et al., 2019; Heffernan et al., 2014; Wuest et al., 2020) currently presents one of the most promising approaches to be used in a global and biotic oriented terrestrial ecosystem reanalysis.

4.2. Agreement on Essential Ecosystem Variables

Agreement on key variables of interest is essential for a targeted reanalysis work flow. The conceptual approach of defining essential variables was first applied by the Global Climate Observing System (GCOS). GCOS developed a selection of Essential Climate Variables (ECVs) which critically contribute to the characterization of climate (Bojinski et al., 2014). Marine scientists agreed on a selection of Essential Ocean Variables (EOVs) in 2010 (Lindstrom et al., 2010). The Group on Earth Observations Biodiversity Observation Network (Scholes et al., 2008; GEO BON, Scholes et al. 2008) developed the concept of Essential Biodiversity Variables (EBVs) to monitor changes in biodiversity (Pereira et al., 2013). Although the various Essential Variable (EV) concepts were developed from a disciplinary perspective, they overlap in terms of
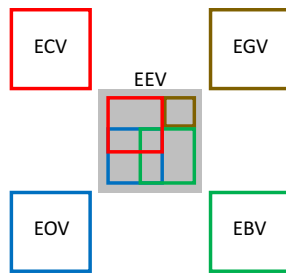
Figure 4. Essential Variables were developed for Climate (ECVs), Biodiversity (EBVs), Ocean (EOVs), and Geodiversity (EGVs). Essential Ecosystem Variables (EEVs) for observation and modeling of ecosystems remain to be defined from the perspective of ecosystem reanalysis. Once the EEVs are agreed upon in a brought consensus, the EEVs will be a subset of these four domains bridging the biotic-abiotic variable space which remains a key challenge.

certain variables and their applicability across domains (Figure 4). For example, EBVs and ECVs overlap in the terrestrial domain of ECVs via the *ecosystem functional attributes* and *ecosystem structure*, while the four EBV classes *genetic composition*, *species population*, *species traits*, and *community composition* are beyond the scope of ECVs. Several concepts have been developed that focus on more systemic approaches to derive EV for the description of ecosystem functions. Haase et al. (2018) proposed to merge the concept of EBVs with the ecosystem integrity concept (Muller et al., 2000). Other concepts focusing on the integration of EBVs and ECVs were framed for Essential Ecosystem Variables (Miguel et al., 2017), Essential Ecosystem Functioning Variables (Alcaraz-Segura et al., 2016), and Essential Ecosystem Service Variables (Balvanera et al., 2016).

In line with these efforts, selected elements of the various EV concepts can be combined to EEVs aiming for the balance between abstraction and necessary precision to deliver meaningful answers with regard to monitoring and understanding global change, pressures and disturbance impacts on terrestrial ecosystems. In this sense, EEV can provide a cross-domain information basis for Earth system modeling (Figure 4), but also data interfaces for the coupling of different model and monitoring approaches through utilizing continuous reanalyzed data sets (Figure 3). A reanalysis framework will thus provide better consideration of biotic-abiotic feedbacks that regulate global change at multiple spatial and temporal levels (e.g., disturbance behavior, ecosystem functions, services, and integrity). Further expanding the reanalyzed variables beyond those of Section 2 will be beneficial for quantifying pressures and drivers of for example, biodiversity and geodiversity loss at individual scales (George et al., 2019; Scholes et al., 2008).

Regarding the available measurement methods, a distinction can be made between measurements using (a) campaign-based data collection and inventories (e.g., habitat mapping, soil mapping, and others), (b) in-situ sensors and (c) remote sensing methods. The constantly growing availability of novel sensors and measurement techniques enables new opportunities to combine different measurement methods and approaches and opens up a number of new opportunities to measure and quantify and assess new "essential variables" like efficiencies or ratios, which were previously very difficult or impossible to be measured or derived on relevant scales. The rapid development of remote sensing sensors and techniques on different platforms (wireless sensor networks, drones, air- and space-borne remote sensing) in particular opens up opportunities for monitoring local, continental up to global applications. A remotely sensed and in-situ record coupling approach of an essential variable needs to fulfill a few prerequisites, before being utilized in an ecosystem reanalysis framework:

1. Adequate predictability of the target variable by the observation system
2. Coupling of different spatial, temporal, and ecosystem scales
3. Transparent processing chain and documentation
4. Consistent, trend-preserving time-series
5. Few or no gaps in the record of continuously processed data
6. Adequate accuracy being proven by validation against in situ network data
7. Similar accuracy level for the whole period
8. Possibility of standardization and thus comparability of the data and data products recorded from remote sensing

Those prerequisites are often given for meteorological records, with operational and therefore continuous remote sensing data and data products dating back several decades. However, for terrestrial variables and in-situ data products this operationality is often not given. Long-term essential variable products could be generated by multi-mission records, measured by sensors not built for the purpose and experimental missions lasting for only a few years. Space agencies should consider those issues for the preparation of follow-on missions. Copernicus and GEO/GEOSS missions have this long-term perspective. In the following sections, we provide a few candidate variables to become essential ecosystem variables. While this list is by no means complete, it is intended to instigate further discussion.

4.3. Remotely Sensed Trait Observations

Remote sensing of physical and biophysical properties of the Earth System is an essential component for reanalysis of Earth and land surface processes such as energy-related, hydrological and biogeochemical processes (Albergel et al., 2018; Kumar et al., 2019; R. H. Reichle, Draper, et al., 2017). Remotely sensed data provide information to initialize and monitor land surface properties such as land cover (Dee et al., 2011) or are assimilated directly using different methods into the model system such as snow properties (Toure et al., 2018), soil water content (R. Reichle et al., 2016; R. H. Reichle et al., 2019), or leaf area index (Albergel et al., 2018; Kumar et al., 2019). Continuous gapless time series with full spatial coverage are available for hydrological key state variables such as soil moisture (Dorigo et al., 2017), plant properties (plant traits) such as LAI (X. Y. Xie et al., 2019), canopy height and aboveground biomass (Duncanson et al., 2020), gross primary production (Zhang et al., 2017) or plant phenology (Cleland et al., 2007) that are important plant traits for terrestrial ecosystem reanalysis.

In contrast to abiotic states, remotely sensed *biotic* states of ecosystems and specifically biotic trait observations from space (Gamon et al., 2019; Kattge et al., 2020; Lausch et al., 2016, 2019) are still in its infancy. The use of the trait approaches from satellite observations refers to changing the perspective from an ecosystem based point of view to the earth observation based point of view. Remote sensing records traits according to the principles of image spectroscopy over the entire electromagnetic spectrum from the visible to the microwave range (Ustin & Gamon, 2010). These spectral traits are crucial to bridge gaps between in-situ and remote sensing approaches (Lausch et al., 2018).

In the last decade a number of trait concepts were developed which can usefully be incorporated to advance the robust concept of biome specific plant functional types. These trait concepts include plant traits (Kattge et al., 2020) such as leaf traits (Moreno-Martinez et al., 2018) or plant functional traits (Bruelheide et al., 2018), geo-traits (Lausch et al., 2019), or the spectral traits (Deans et al., 2012; Lausch et al., 2016). Plant traits are genetic, anatomical, morphological, biochemical, biophysical, physiological, structural or phenological characteristics, and properties of organisms (Kattge et al., 2020). Traits and their chances (trait-variations) help us to understand, explain and predict where organisms live, how they react to environmental changes and how they interact with different stressors, disorders or resource constraints (Green et al., 2008). "Ecologists are increasingly looking at traits - rather than species - to measure the health of ecosystems" (Cernansky, 2017). Therefore, traits are crucial indicators or filters to measure and assess the ecosystem state, environmental changes, land use intensity, stress or disturbances in ecosystem processes (Averill et al., 2019; Gámez-Virués et al., 2015). Traits exist and can be measured, described and evaluated on all spatio-temporal scales (Abelleira Martínez et al., 2016). They represent a crucial bridging approach to standardization and monitoring of biotic-abiotic interactions (Lausch et al., 2016, 2019).

Global scale data availability meets the reanalysis' demand for high resolution data coverage back in time over decades. The trait observation centered approach has potential to elucidate the largely unknown macrosystem ecological processes (Fei et al., 2016; Gholz & Blood, 2016; Heffernan et al., 2014) and integrate these into ecosystem models. The strong causal connection to earth system processes such as nutrient cycling (Sitzia et al., 2018), surface hydrology (Matheny et al., 2017; Oddershede et al., 2019), productivity of ecosystems (Lees et al., 2018), observing terrestrial ecosystems and the carbon cycle from space (Schimel et al., 2015, 2019), mapping plant functional diversity (Schneider et al., 2017; Stavros et al., 2017) and biodiversity (Averill et al., 2019; Kissling et al., 2018; Lausch et al., 2016) poise the trait observation centered concept for future reanalysis.

4.4. In-Situ Long Term Ecosystem Observatories

Data relevant to ecosystem structure and covering a range of biotic-abiotic variables are measured at numerous sites globally. These sites often cover different ecosystem compartments providing ground truthing to satellite data and important information to study multi-scale processes from site-to-global scale. Scientific networks undertaking these measurements include the Critical Zone Observatories (Brantley et al., 2017), the Integrated Carbon Observation System (ICOS, Lavric et al., 2016) and FluxNet network (Papale et al., 2006), and the continental-global Long Term Ecosystem Research Networks (LTER, Keller et al., 2008; Mirtl et al., 2018; Teeri & Raven, 2002). The Critical Zone Observatories focus on geophysical

characterizations of the zone between bedrock and atmosphere (Baatz et al., 2018; Weintraub et al., 2019). The observation strategy of CZO sites is driven by the site's principle investigators. This means that observation technology, observation frequency, and data reporting are largely not congruent for many sites, making integration of data into models and characterizing observation uncertainty difficult over large areas. Recent efforts incentivize more standardized observation technology and data reporting (Brantley et al., 2017). The operational Integrated Carbon Observation System (Lavric et al., 2016) provides continuous, high quality and standardized abiotic and biotic measurements through a dedicated network of observation stations in Europe (https://www.icos-cp.eu/). The main goal of ICOS is the detection and quantification of European greenhouse gas fluxes. Protocols standardize target observations, pre-scribe transparent data processing for sites, for a consistent level of accuracy for the observation period. Notable biotic-abiotic ICOS observations in the standard protocol for level 1 sites are above- and below-ground biomass, net ecosystem exchange, CO_2, H_2O, H, CH_4, and N_2O exchange between land surface and atmosphere, and more. ICOS sites therefore leverage data quality of European FluxNet sites to enable calibration, validation and data assimilation into carbon- and ecosystem reanalysis.

LTER enables ecosystem research and observation since decades (Mirtl et al., 2018). LTER focusses on ecosystem research and observations of ecosystem relevant biotic, ecologic variables. In Europe, the emerging Integrated European Long-Term Ecosystem, critical zone & socio-ecological Research Infrastructure (eLTER RI, http://www.lter-europe.net/elter-esfri) aims at the systematic, harmonized and sustainable gathering of integrated terrestrial ecosystem data across 250 sites to enable ecosystem reanalysis at the European scale. The terrestrial ecosystem reanalysis strategy was also addressed in the foundation of the National Ecological Observatory Network (NEON) of the United States (Keller et al., 2008; Teeri & Raven, 2002). Monitoring approaches of eLTER RI and NEON aim at the coverage of bio-ecological, geoscientific, and socio-ecological components as well as representative coverage of the most important ecological, climatic and geographical gradients. Besides site level observations, eLTER RI fosters integration of long-term monitoring schemes with the United Nations Economic Commission for Europe (UNECE) Working Group International Cooperative Program (ICP) on "Integrated Monitoring of Ecosystems" and system-focused sites of ICP Forest. Given the implementation of these standardized protocols and data reporting for multi-variate in-situ observations (Firbank et al., 2017), the networks provide a database for site-level to continental scale terrestrial ecosystem reanalysis as has been demonstrated already for FluxNet and river discharge monitoring in Section 2.

4.5. Existing Specific Biotic In-Situ Data

Biotic data can also be rather abstract conceptual data such as species threat indices of abundance estimated from population samples, or it can be detailed phylogenetic, taxonomic and family specific data. Proenca et al. (2017) list monitoring schemes including animal and bird life of international character with at least continental coverage reaching back to 1966. While in those early years, only few countries applied national monitoring programs, by 2005 already 20 European countries adopted standardized bird-monitoring programs (Gregory et al., 2005), and by 2010, the efforts reached global scale through the Earth Observation Biodiversity Network embracing less developed regions (GEO BON, Pereira et al., 2013). The biodiversity data are an indicator for changes in land management, land use and their intensity, ecosystem structure, its functionality, state and parameterization (e.g., Kamp et al., 2018; Pereira et al., 2013). While biodiversity is often stronger affected by land use, fungi and fungal groups are impacted stronger by climatic drivers and soil states such as calcium and phosphorus concentration, and pH (Tedersoo et al., 2014). The Projecting Response of Ecological Diversity In Changing Terrestrial Systems (PREDICTS, Hudson et al., 2017) is a database resulting from anterior efforts, characterizing numerous aspects of biotic populations in a structured way. One data source mined by PREDICTS is the Global Biodiversity Information Facility (GBIF, 2020, https://www.gbif.org). GBIF offers more than 1 billion records within 42,000 data sets on biodiversity and trait information in a citable and open source manner while unstructured. One particularly large data set on flora and fauna characteristics is the Plant Traits Database with more than 6.9 million trait records and 148,000 plant taxa (e.g., Kattge et al., 2011, 2020). The international tree ring data bank is another valuable set of spatio-temporal data to include useful biogeographical information through dendrochronologic measurements (Babst et al., 2017). Although challenges remain with regard to spatial, environmental, and taxonomic representativity (S. Zhao et al., 2019), dendrochronological data are an important indicator for

ecosystem stress through heat, drought, and flooding (A. P. Williams et al., 2020) frequently used in climate reconstruction over centuries.

In addition to these diverse but networked long term in situ data, high-throughput Biodiversity Data (HBD, Makiola et al., 2020; Wuest et al., 2020) are becoming available in the near future. HBD on environmental DNA will be available from DNA and RNA sequencing at selected sites (Bush et al., 2017). Also called next-generation biomonitoring, HBD produces data sets on ecosystem compositions and allows macroecological modeling at species to community level (Bani et al., 2020). Previously mentioned modeling frameworks jointly with HBD may allow the resolution of species specific causalities for macrosystem-ecological modeling (Cabral et al., 2019; Wuest et al., 2020) to establish a robust data foundation for producing reanalyzed biotic ecosystem states. Which data can be assimilated in a reanalysis or model data fusion framework remains a question of harmonization and standardization for the specific reanalysis objective.

4.6. Example of a Site Level Ecosystem Reanalysis for the Harvard Forest

Raiho et al. 2020 provides an example of assimilating dendrochronological data into a forest gap model (H. H. Shugart & Smith, 1996) to understand what drives uncertainty in hindcasts of forest stand development.

Forest stand development is driven by competition between tree species for light, water, and nutrients initializing when a gap is made in the forest canopy by a disturbance. Following canopy disturbance, initially fast-growing shade intolerant species are dominant and eventually slow-growing, shade tolerant species become dominant (H. H. Shugart, Jr. & West, 1980). The forest gap model, LINKAGES, simulates competition between individual trees by incrementing each individual tree's diameter at breast height (DBH) based on limiting environmental factors: available light, soil moisture, and soil nitrogen (Post & Pastor, 1996; Figure 5a). These DBH values are then aggregated into annual species-level aboveground biomass using allometric relationships for each tree species. These species-level aboveground biomass measurements are then easily comparable to both terrestrial models that do not produce individual level DBH values and a variety of ecosystem data sources including tree ring derived aboveground biomass measurements. Typically, forest gap models are run without any data constraints on aboveground biomass. Raiho et al. 2020 use data assimilation to constrain LINKAGES biomass reconstructions with dendrochronological data, which improves model simulation of competition between individual trees. To assimilate species-level biomass into LINKAGES, Raiho et al. 2020 develop the Tobit Wishart Ensemble Filter (TWEnF). The TWEnF works very similarly to an EnKF but accounts for zero-truncated data, common in ecological datasets, and incorporates an estimate of process error (Raiho et al., 2020).

To demonstrate the ability of the TWEnF to improve species biomass reconstruction, Raiho et al. 2020 consider the well-documented forest site, the Lyford Plot at Harvard Forest (Eisen, 2015). Land at Harvard Forest was cleared for agriculture (Foster et al., 1998) in 1900. The Lyford plot spans 3 ha in a temperate climate and thin glacial till soil type. Since 1900, the Lyford plot has been regrowing temperate deciduous trees including: red oak (*Quercus rubra*), red maple (*Acer rubrum*), yellow birch (*Betula alleghaniensis*), American beech (*Fagus granifolia*), and eastern hemlock (*Tsuga canadensis*). Within the Lyford plot red oak has become the dominant species (Figure 5b), unlike the surrounding forests where red maple has become the dominant (Abrams, 1998). We present an analysis at one site, noting this type of analysis could be expanded to scales where large scale tree ring data are available (See international tree ring database, ITRDB, Babst et al., 2017).

We show results for an open loop run without data assimilation, constrained model predictions with partial data assimilation, and model predictions with data assimilation of the full time period (Figure 5c). For simplicity in this example, we show total aboveground biomass which is the sum of species-level biomasses. Figure 5c demonstrates how the reconstruction of total aboveground biomass of red oak (*Quercus rubra*) at Harvard Forest changes depending on the amount of data that was assimilated. In the open loop scenario, there is very large uncertainty about the total aboveground biomass in 2010 because we incorporated parameter, meteorological, and process uncertainties. This depicts a realistic forecast including uncertainty of over 50 years of forest stand development. Raiho et al. (2020) found that constraining initial conditions alone with data also had a large effect on reconstruction uncertainty. The second partial data assimilation constraint shows this effect where assimilating data to 1984 greatly constrains uncertainty in 2010 but does
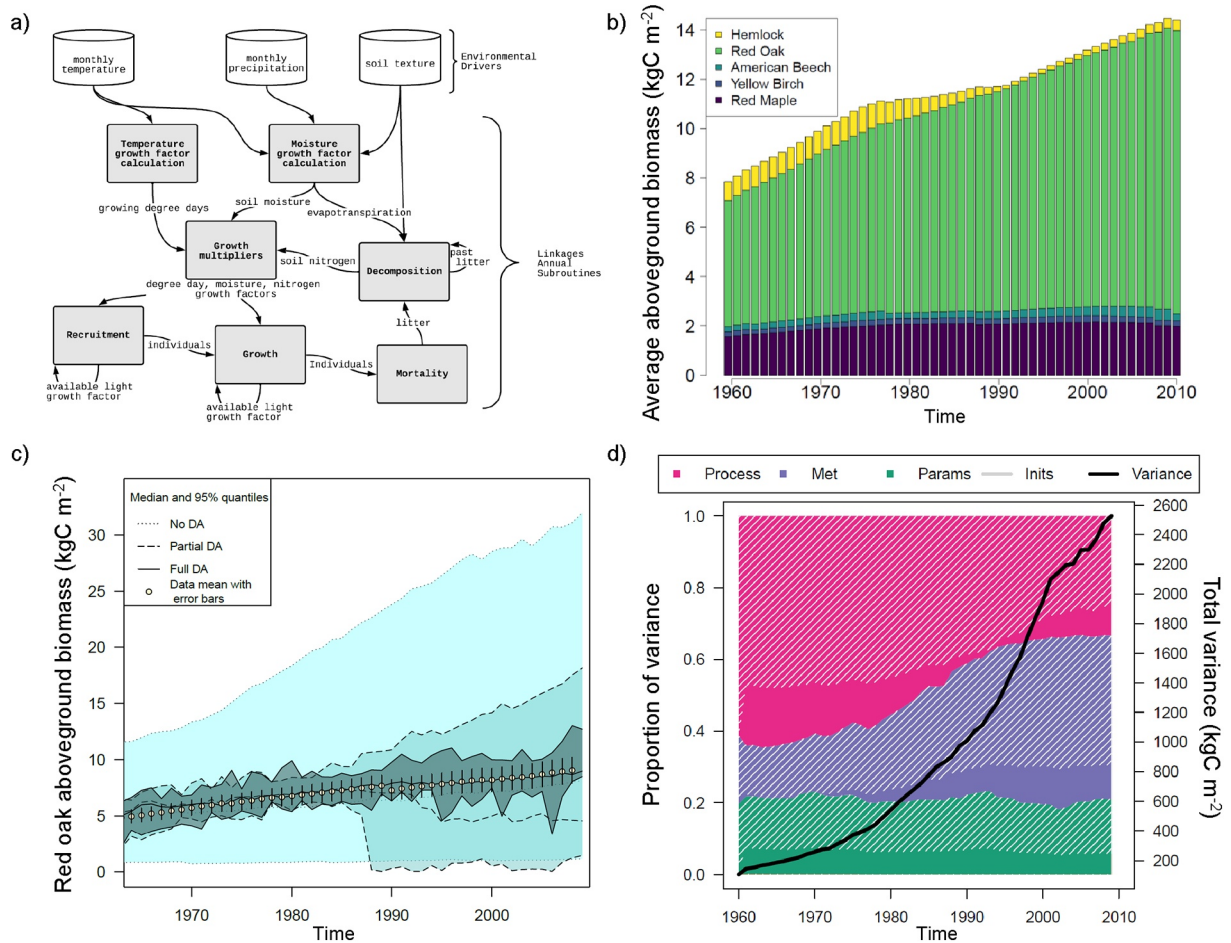
Figure 5. (a) Conceptual diagram of the forest gap model LINKAGES. Each top cylinder represents the inputs to the model, and gray boxes represent a subroutine within the model. (b) The stacked bar plot shows the posterior mean of species-level estimated biomass from tree rings collected at the Harvard Forest Lyford Plot. (c) Total aboveground biomass distribution for the dominant species red oak (*Quercus rubra*) simulated by three LINKAGES runs are shown in this time series with different amounts of data constraint, demonstrating the usefulness of reanalysis on improving predictions from LINKAGES. (d) The relative contribution of each type of variance to total aboveground biomass variance. Hashed areas are the relative variances that can be attributed to the covariance with initial conditions. Over time initial condition uncertainty covariance together with meteorological uncertainty (purple) accounted for a larger proportion of total variance while initially process uncertainty dominates. Total variance over time is shown as black line with the scale on the right hand *y*-axis.

not result in red oak dominance. Interestingly, this is similar to a prediction made by Lorimer (1984). Finally, the full data assimilation scenario shows that the TWEnF constrains aboveground biomass predictions well. Furthermore, the relative contribution of each type of variance to total aboveground biomass variance was analyzed. Individual contributions change over the assimilation period, providing information on reasons and origins of forecast uncertainty.

The site-specific reanalysis of species-level aboveground biomass demonstrates how data assimilation can be used to provide further insights into processes represented in models and improve predictions. Comparing the partial data assimilation to the full data assimilation scenario demonstrates the importance of iteratively updating model forecasts using new observations. The results show the framework's ability to predict competitive dynamics between forest species counterintuitive to conservative experts and model prediction. The framework enabled the model to learn the competitive mechanisms behind red oak outperforming red maple populations under sites-specific conditions with fewer canopy disturbances. Furthermore, variance partitioning between the uncertainty components, parameter, meteorological, process, and initial conditions, revealed which aspects of uncertainty were most important to constrain to improve long-term prediction (Figure 5d). Initial conditions were found to be most important over the time period, where including initial conditions reduced total forecast uncertainty over a 50-years time period by more than 20%. Process

uncertainty was also an important aspect of uncertainty initially followed by an increase in meteorological uncertainty over time.

5. Conclusions

The review analyzes the state-of-the-art in methods, recent developments and prospects of reanalysis for three subcomponents of the Earth system (atmosphere, ocean, and land). It focusses on 21st century reanalysis products including ecosystem reanalyzes. Other studies reviewed reanalysis in climate and atmospheric science (Dee et al., 2011; Fujiwara et al., 2017), and the physical (Storto et al., 2017) and biogeochemical oceanic research (Fennel et al., 2019). We outline major advances using exemplary reanalysis products while we acknowledge that the discussion of several excellent reanalysis products is not included here for reason of space. Recently, networks of distributed in-situ sensors such as buoys and biogeochemical Argo floats (Fennel et al., 2019), eddy covariance stations (Peylin et al., 2016), surface water runoff observations (Hobeichi et al., 2019) and meteorological station data (Hersbach et al., 2020) were used in reanalysis of physical and biogeochemical Earth system processes. These reanalyzes highlight progress in predicting particularly terrestrial ECV. Novel concepts on global biotic trait observation approaches (e.g., plant traits, TRY trait data base, Kattge et al., 2011, 2020), coupled with satellite based earth observation for spectral traits (Lausch et al., 2019), and integrated ecosystem observatories at continental (e.g., Europe: eLTER Mirtl et al., 2018) to global scale (GEO BON, Pereira et al., 2013) promise meaningful harmonized and standardized in-situ data including more biotic variables for reanalysis. This allows for establishing new variable concepts, merging ECVs and EBVs into EEVs. In this sense, a prioritization of environmental variables against the background of the data requirements of the reanalysis can also provide important support for the development of future integrated environmental monitoring programs. Specific and targeted new essential variables are set forth to address the needed terrestrial biotic-abiotic feedback mechanisms at a hyper-resolution global modeling scale through terrestrial ecosystem reanalysis.

Data Availability Statement

No data were used in producing this manuscript.

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